

```
c=====
c      Solves 1-d linear boundary value problem
c
c      u''(x) = f(x)   on   x = [0,1]; u(0) = u0, u(1) = u1
c
c      using second-order finite difference technique and
c      LAPACK tridiagonal solver DGTSV.
c=====
program          bvp1d
implicit          none
integer           i4arg
```

```

c-----
c      Extrema of problem domain; note that this approach
c      of defining extrema as parameters makes it easier
c      to generalize program to arbitrary domains.
c-----

      real*8          xmin,           xmax
      parameter       ( xmin = 0.0d0,   xmax = 1.0d0 )

c-----
c      Maximum problem size (2**20 + 1)
c-----

      integer          maxn
      parameter       ( maxn = 1 048 577 )

c-----
c      Storage for discrete x-values, unknowns, exact
c      solution and right hand side values
c-----

      real*8          x(maxn),        u(maxn),
      &                  ueexact(maxn),  f(maxn)

c-----
c      Storage for main, upper and lower diagonals of
c      tridiagonal system, and right-hand-side vector
c      for use with LAPACK routine DGTSV
c-----

      real*8          d(maxn),        du(maxn),
      &                  dl(maxn),        rhs(maxn)
      integer          nrhs,
                      info

c-----
c      Discretization level and size of system (# of discrete
c      unknowns)
c-----

      integer          level,         n,
      &                  option

```

```

c-----
c      Mesh spacing and related constants (1/h**2, -2/h**2)
c-----
      real*8          h,           hm2,           m2hm2
      real*8          rmserr

c-----
c      Argument parsing.
c-----

      level = i4arg(1,-1)
      if( level .lt. 0 ) go to 900
      n = 2 ** level + 1
      if( n .gt. maxn ) then
         write(0,*) 'Insufficient internal storage'
         stop
      end if
      option = i4arg(2,0)

c-----
c      Set up finite-difference 'mesh' (discrete x-values)
c      and define some useful constants.
c-----

      h      = 1.0d0 / (n - 1)
      do j = 1 , n
         x(j) = xmin + (j - 1) * h
      end do
      hm2   = 1.0d0 / (h * h)
      m2hm2 = -2.0d0 / (h * h)

c-----
c      This only ensures that x(n) = xmax EXACTLY and is not
c      essential.
c-----

      x(n) = xmax

```

```

c-----
c      Set up exact solution and right hand side vector.
c-----
c      call exact(uexact,f,x,n)

c=====
c      Set up tridiagonal system. Note that indexing on
c      lower diagonal is always (j-1) when implementing the
c      j'th equation.
c=====

c-----
c      Left boundary: u(1) = u_0
c-----
d(1)      = 1.0d0
du(1)     = 0.0d0
rhs(1)    = uexact(1)

c-----
c      Interior: Second order FDA of ODE.
c-----

do j = 2 , n - 1
  dl(j-1) = hm2
  d(j)    = m2hm2
  du(j)   = hm2
  rhs(j)  = f(j)
end do

c-----
c      Right boundary: u(n) = u_1
c-----

dl(n-1)   = 0.0d0
d(n)      = 1.0d0
rhs(n)    = uexact(n)

```

```

c=====
c      Solve tridiagonal system.
c=====

      nrhs = 1
      call dgtsv( n, nrhs, dl, d, du, rhs, n, info )

      if( info .eq. 0 ) then
c-----
c      Solver successful, output either (x_j, u_j) or
c      (x_j, error_j) to stdout.  Also compute rms error
c      and output to standard error.
c-----
      rmserr = 0.0d0
      do j = 1 , n
         if( option .eq. 0 ) then
            write(*,*) x(j), rhs(j)
         else
            write(*,*) x(j), (uexact(j) - rhs(j))
         end if
         rmserr = rmserr + (uexact(j) - rhs(j)) ** 2
      end do
      rmserr = sqrt(rmserr / n)
      write(0,*) 'rmserr = ', rmserr
      else
c-----
c      Solver failed.
c-----
      write(0,*) 'bvp1d: dgtsv() failed, info = ', info
      end if

      stop

```

```

900 continue
    write(0,*) 'usage: bvp1d <level> [<option>]'
    write(0,*)
    write(0,*) '           Specify option .ne. 0 for output'
    write(0,*) '           of error instead of solution'
    stop

end

c=====
c      Computes exact values for u(x) (unknown function)
c      and f(x) (right hand side function).  x array must
c      have been previously defined.
c=====

subroutine exact(u,f,x,n)

    implicit none
    integer n
    real*8 u(n), f(n), x(n)

    real*8 pi2
    integer j

    pi2 = 8.0d0 * atan(1.0d0)
    do j = 1 , n
        u(j) = sin(pi2 * x(j))
        f(j) = -pi2 * pi2 * u(j)
    end do

    return

end

```

```

        SUBROUTINE DGTSV( N, NRHS, DL, D, DU, B, LDB, INFO )
*
* -- LAPACK routine (version 2.0) --
* Univ. of Tennessee, Univ. of California Berkeley, NAG Ltd.,
* Courant Institute, Argonne National Lab, and Rice University
* September 30, 1994
*
* .. Scalar Arguments ..
INTEGER           INFO, LDB, N, NRHS
*
* ..
* .. Array Arguments ..
DOUBLE PRECISION  B( LDB, * ), D( * ), DL( * ), DU( * )
*
* ..
*
* Purpose
* ======
*
* DGTSV solves the equation
*
*     A*X = B,
*
* where A is an N-by-N tridiagonal matrix, by Gaussian elimination with
* partial pivoting.
*
* Note that the equation A'*X = B may be solved by interchanging the
* order of the arguments DU and DL.
*
* Arguments
* ======
*
* N      (input) INTEGER
*        The order of the matrix A.  N >= 0.
*
* NRHS   (input) INTEGER

```

```

*
*   The number of right hand sides, i.e., the number of columns
*   of the matrix B.  NRHS >= 0.
*
*   DL      (input/output) DOUBLE PRECISION array, dimension (N-1)
*   On entry, DL must contain the (n-1) subdiagonal elements of
*   A.
*   On exit, DL is overwritten by the (n-2) elements of the
*   second superdiagonal of the upper triangular matrix U from
*   the LU factorization of A, in DL(1), ..., DL(n-2).
*
*   D      (input/output) DOUBLE PRECISION array, dimension (N)
*   On entry, D must contain the diagonal elements of A.
*   On exit, D is overwritten by the n diagonal elements of U.
*
*   DU     (input/output) DOUBLE PRECISION array, dimension (N-1)
*   On entry, DU must contain the (n-1) superdiagonal elements
*   of A.
*   On exit, DU is overwritten by the (n-1) elements of the first
*   superdiagonal of U.
*
*   B      (input/output) DOUBLE PRECISION array, dimension (LDB,NRHS)
*   On entry, the N-by-NRHS right hand side matrix B.
*   On exit, if INFO = 0, the N-by-NRHS solution matrix X.
*
*   LDB    (input) INTEGER
*   The leading dimension of the array B.  LDB >= max(1,N).
*
*   INFO   (output) INTEGER
*   = 0:  successful exit
*   < 0:  if INFO = -i, the i-th argument had an illegal value
*   > 0:  if INFO = i, U(i,i) is exactly zero, and the solution
*         has not been computed.  The factorization has not been
*         completed unless i = N.
*

```

```

* =====
*
* .. Parameters ..
DOUBLE PRECISION    ZERO
PARAMETER          ( ZERO = 0.0D+0 )
*
* ..
* .. Local Scalars ..
INTEGER             J, K
DOUBLE PRECISION    MULT, TEMP
*
* ..
* .. Intrinsic Functions ..
INTRINSIC          ABS, MAX
*
* ..
* .. External Subroutines ..
EXTERNAL            XERBLA
*
* ..
* .. Executable Statements ..
*
INFO = 0
IF( N.LT.0 ) THEN
    INFO = -1
ELSE IF( NRHS.LT.0 ) THEN
    INFO = -2
ELSE IF( LDB.LT.MAX( 1, N ) ) THEN
    INFO = -7
END IF
IF( INFO.NE.0 ) THEN
    CALL XERBLA( 'DGTSV ', -INFO )
    RETURN
END IF
*
IF( N.EQ.0 )
$    RETURN
*
```

```

DO 30 K = 1, N - 1
  IF( DL( K ).EQ.ZERO ) THEN
*
*      Subdiagonal is zero, no elimination is required.
*
*      IF( D( K ).EQ.ZERO ) THEN
*
*          Diagonal is zero: set INFO = K and return; a unique
*          solution can not be found.
*
*          INFO = K
*          RETURN
*          END IF
ELSE IF( ABS( D( K ) ).GE.ABS( DL( K ) ) ) THEN
*
*          No row interchange required
*
*          MULT = DL( K ) / D( K )
*          D( K+1 ) = D( K+1 ) - MULT*DU( K )
*          DO 10 J = 1, NRHS
*              B( K+1, J ) = B( K+1, J ) - MULT*B( K, J )
10        CONTINUE
*          IF( K.LT.( N-1 ) )
*              DL( K ) = ZERO
*          ELSE
*
*              Interchange rows K and K+1
*
*              MULT = D( K ) / DL( K )
*              D( K ) = DL( K )
*              TEMP = D( K+1 )
*              D( K+1 ) = DU( K ) - MULT*TEMP
*              IF( K.LT.( N-1 ) ) THEN
*                  DL( K ) = DU( K+1 )

```

```

        DU( K+1 ) = -MULT*DL( K )
      END IF
      DU( K ) = TEMP
      DO 20 J = 1, NRHS
        TEMP = B( K, J )
        B( K, J ) = B( K+1, J )
        B( K+1, J ) = TEMP - MULT*B( K+1, J )
20      CONTINUE
      END IF
30 CONTINUE
      IF( D( N ).EQ.ZERO ) THEN
        INFO = N
        RETURN
      END IF
*
*   Back solve with the matrix U from the factorization.
*
      DO 50 J = 1, NRHS
        B( N, J ) = B( N, J ) / D( N )
        IF( N.GT.1 )
$          B( N-1, J ) = ( B( N-1, J )-DU( N-1 )*B( N, J ) ) / D( N-1
        DO 40 K = N - 2, 1, -1
          B( K, J ) = ( B( K, J )-DU( K )*B( K+1, J )-DL( K )*
$                        B( K+2, J ) ) / D( K )
40      CONTINUE
50 CONTINUE
*
      RETURN
*
*   End of DGTSV
*
      END

```

```
#####
# Building 'bvp1d' and sample output on sgi1.
#####
sgi1% pwd; ls
/usr/people/phys410/linsys/ex2
Makefile bvp1d.f gperr gpsoln8

sgi1% make
f77 -g -64 -c bvp1d.f
f77 -g -64 -L/usr/local/lib bvp1d.o -lp329f -llapack -lblas -o bvp1d

sgi1% bvp1d
usage: bvp1d <level> [<option>]

Specify option .ne. 0 for output
of error instead of solution

sgi1% bvp1d 4
0.00000000000000E+00 -5.5511151231257827E-16
6.25000000000000E-02 0.3876394685723090
0.1250000000000000 0.7162643420150174
0.1875000000000000 0.9358444623383684
0.2500000000000000 1.012950746721879
0.3125000000000000 0.9358444623383684
0.3750000000000000 0.7162643420150175
0.4375000000000000 0.3876394685723092
0.5000000000000000 -2.2204460492503131E-16
0.5625000000000000 -0.3876394685723097
0.6250000000000000 -0.7162643420150181
0.6875000000000000 -0.9358444623383690
0.7500000000000000 -1.012950746721880
0.8125000000000000 -0.9358444623383690
0.8750000000000000 -0.7162643420150181
0.9375000000000000 -0.3876394685723097
```

```

1.000000000000000 -2.4492935982947064E-16
rmserr = 8.8841389573651453E-03

#####
# Simple convergence test: solve BVP on a sequence of
# levels (h, h/2, h/4, h/16, etc.), redirect stdout to
# /dev/null so that only the overall RMS error appears on
# terminal. Note how RMS error goes down by very nearly
# a factor of 4 at each successive level, indicating
# O(h^2) convergence.
#####
sgi1% foreach level (4 5 6 7 8 9 10)
foreach? bvp1d $level > /dev/null
foreach? end
rmserr = 8.8841389573651453E-03
rmserr = 2.2413991373367772E-03
rmserr = 5.6382739826354859E-04
rmserr = 1.4145099550532311E-04
rmserr = 3.5428279660444339E-05
rmserr = 8.8654982501522291E-06
rmserr = 2.2174426911240527E-06

#####
# Making output files for subsequent plotting via gnuplot.
# See Class Notes for postscript.
#####
sgi1% bvp1d 8 > out8
rmserr = 3.5428279660444339E-05
sgi1% bvp1d 5 1 > err5
rmserr = 2.2413991373367772E-03
sgi1% bvp1d 6 1 > err6
rmserr = 5.6382739826354859E-04
sgi1% bvp1d 7 1 > err7
rmserr = 1.4145099550532311E-04

```

```
#####
# Gnuplot "script" (gpsoln8) for making plot of level-8
# solution
#####
sgi1% cat gpsoln8
set terminal postscript portrait
set size 0.760,1.0
set output "soln8.ps"
plot [0:1] [-1:1] "out8"
quit

#####
# Make the plot
#####
sgi1% gnuplot < gpsoln8

#####
# Gnuplot "script" (gperr) for making plot of error from
# level 5, 6 and 7 calculations
#####
sgi1% cat gperr
set terminal postscript portrait
set size 0.760,1.0
set output "err567.ps"
plot "err5", "err6", "err7"
quit

#####
# Make the plot
#####
sgi1% gnuplot < gperr
```

```

sgi1% ls
Makefile      bvp1d.f      err5       err6       gperr      out8
bvp1d*        bvp1d.o      err567.ps   err7       gpsoln8    soln8.ps

#####
# Clean-up: Note, the Makefile used here has separate
# 'clean' and 'vclean' (very clean) targets.
#####
sgi1% make clean
rm *.o
rm bvp1d

sgi1% ls
Makefile      err5       err6       gperr      out8
bvp1d.f      err567.ps   err7       gpsoln8    soln8.ps

sgi1% make vclean
rm *.o
Cannot access *.o: No such file or directory
make: [clean] Error 2 (ignored)
rm bvp1d
Cannot access bvp1d: No such file or directory
make: [clean] Error 2 (ignored)
rm err[0-9]*
rm out[0-9]*
rm *.ps

sgi1% ls
Makefile      bvp1d.f      gperr      gpsoln8

```

```

.IGNORE:

F77_COMPILE = $(F77) $(F77FLAGS) $(F77CFLAGS)
F77_LOAD    = $(F77) $(F77FLAGS) $(F77LFLAGS)

.f.o:
    $(F77_COMPILE) $*.f

EXECUTABLES = bvp1d

all: $(EXECUTABLES)

bvp1d: bvp1d.o
    $(F77_LOAD) bvp1d.o -lp410f -llapack $(LIBBLAS) -o bvp1d

clean:
    rm *.o
    rm $(EXECUTABLES)

#####
# Note the 'vclean' target: 'make vclean' results in
# 'make clean' followed by removal of input and output
# data files and postscript files.
#####
vclean: clean
    rm err[0-9]*
    rm out[0-9]*
    rm *.ps

```



