

Numerical General Relativistic Magnetohydrodynamics

Astronomy Theory Meeting

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Outline

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- Plasma
- Astrophysical Phenomenon
- Magnetohydrodynamics
- Solver
- Metric
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- Turbulence
- Current Project

Motivation

- What is General Relativistic Magnetohydrodynamics?
 - The study of compressible, conducting fluids as they exist in curved spacetime.
 - Generally involve the study of three key components
 - Curved Spacetime
 - Hydrodynamic Stress–Energy Tensor
 - Electromagnetism Stress–Energy Tensor
 - Magnetohydrodynamic Stress–Energy Tensor
- Why is magnetohydrodynamics considered important?
 - Magnetic fields are fundamental to many astrophysical phenomenon
 - Currently believed to be a model for the dynamics of an AGN, and Supernovae

Plasma

- Plasma Physics
 - A plasma is a highly ionized gas. When the plasma constituents are sufficiently collisional we use single fluid magnetohydrodynamics to describe the system.
 - If the conductance is sufficiently large we can neglect the resistive terms, thus have an ideal conductor
 - If the system has isotropic pressure, we assume heat flow is small and can neglect the viscous terms, thus have an ideal fluid
- dimensionless plasma parameters
 - Λ - the number of particles in the Debye sphere
 - β - the ratio of the thermal pressure to the magnetic pressure
 - δ - the ratio of the rest mass energy to the magnetic energy

Astrophysical Phenomenon

- Accretion Disks

- Material that is caught in the gravitational field of a massive body
- May come from a binary star
- accretion phenomenon is thought to be much more efficient than nuclear fusion

- Relativistic Jets

- A steady collimated beam of material emanating from a central body
- Still not well understood
- Mechanisms for collimation of the jet is still an open question

- Active Galactic Nuclei

- This astrophysical phenomenon is said to be at the centre of an active galaxy, understanding this may lead to a better understanding of the origins of our own galaxy

- Angular Momentum Transport

- There is still ongoing debate as to the mechanism that allows for angular momentum transport within accretion disks.

Magnetohydrodynamic Dimensionless Numbers

- Hydrodynamic dimensionless numbers
 - Knudsen number - $\lambda/L \ll 1$
 - Reynolds number (Re) - VL/ν
 - Mach number (M) - V/c_s
- Where
 - λ - mean free path between particles
 - L - characteristic length scale $\sim R_{EventHorizon}$
 - V - characteristic velocity scale $\sim c$
 - ν - fluid viscosity $\rightarrow 0$
 - c_s - speed of sound $\sim \sqrt{\frac{P}{\rho_0}}$

Magnetohydrodynamic Dimensionless Numbers

- Additional dimensionless numbers when considering magnetic field contributions
 - Magnetic Reynolds number (R_M) - VL/η
 - beta (β) - $P_{thermal}/P_{magnetic}$
 - Alfvén number (a) - V/v_A
 - Ratio of energy densities (δ) - E_B/E_{rest}
- where
 - v_A - the Alfvén velocity = $B/\sqrt{\rho_o}$
 - η - the resistivity $\rightarrow 0$
 - $E_B \sim |B|^2$
 - $E_{rest} \sim \rho_o$
- The free parameters to survey are
 - β , M , a , and δ

General Relativistic Magnetohydrodynamics

- The Conservative Equations

- General conservative form

$$\frac{\partial \mathbf{q}}{\partial t} + \nabla f(\mathbf{q}) = \Sigma(\mathbf{q}) \neq \Sigma(\mathbf{q}, \nabla \mathbf{q})$$

- This is a system of hyperbolic differential equations
- Conservative variables \mathbf{q}
- Finite volume techniques have been employed to solve these equations
- Integral form - allows for shock capturing
- Typically the conservative variables (\mathbf{q}) will be functions of what are known as primitive variables (\mathbf{p}), $\mathbf{q} \rightarrow \mathbf{q}(\mathbf{p})$
- Primitive variable conversion is required to obtain the required physical variables, in GR there is no closed form solution to this inversion
- Equation of State also requires primitive variables

Conservation Form

- To consider the evolution of a magnetohydrodynamic system we use the conservation equations for baryons, energy–momentum, and the magnetic induction equation, as the fluid flows through some volume of space
- Baryon: $\nabla_{\mu}(J^{\mu}) = 0$, $J^{\mu} = \rho_o u^{\mu}$
 - u^{μ} is the fluid's 4-velocity
 - This is an expression for the conservation of matter
- Energy–Momentum: $\nabla_{\mu} T^{\mu\nu} = 0$
 - Conservation of Mass
 - Conservation of Momentum
- Induction Equation: $\nabla_{\mu} {}^*F^{\mu\nu} = 0$
 - ${}^*F^{\mu\nu}$ is the dual Faraday tensor
 - Using differential geometry terminology, just to say we use Maxwell's relations

Equation of State

- To close the system of equations, we also need an equation of state

- Ideal Gas Equation of state

- $P = (\Gamma - 1)\rho_o\epsilon$
 - P - Pressure
 - $\rho = \rho_o(1 + \epsilon)$ - total mass energy density
 - Γ - adiabatic constant
 - ϵ - specific energy
 - ρ_o - rest mass density
 - $h = 1 + \epsilon + \frac{P}{\rho}$ - specific enthalpy

- Realistic Gas Equation of state

- $P = \frac{\rho\epsilon[\rho\epsilon+2\rho]}{3(\rho\epsilon+\rho)}$
 - $h = \frac{5P}{2\rho} + \sqrt{\frac{9P^2}{4\rho^2} + 1}$ - specific enthalpy

Relativistic Magnetohydrodynamics

- The Relativistic MHD Equations in Conservative Form

$$\begin{aligned}\partial_t(\sqrt{-g}\rho_o u^t) + \partial_i(\sqrt{-g}\rho_o u^i) &= 0 \\ \partial_t(\sqrt{-g}T_\nu^t) + \partial_i(\sqrt{-g}T_\nu^i) &= \sqrt{-g}T^{\mu\kappa}\partial_\mu g_{\nu\kappa} - \sqrt{-g}T_\lambda^\kappa\Gamma_{\nu\kappa}^\lambda \\ \partial_t(\sqrt{-g}B^i) + \partial_j(\sqrt{-g}(u^j b^i - u^i b^j)) &= 0 \\ \partial_i(\sqrt{-g}B^i) &= 0\end{aligned}$$

where g is the determinant of the metric and

$$\begin{aligned}T^{\mu\nu} &= (\rho + P + b^2)u^\mu u^\nu + (P + \frac{1}{2}b^2)g^{\mu\nu} - b^\mu b^\nu \\ b^\mu &\equiv \frac{1}{2}\epsilon^{\mu\nu\kappa\lambda}u_\nu F_{\lambda\kappa}\end{aligned}$$

Metrics

- Life would be considerably easier if all matter was too small to distort space and time surrounding them
- However this would be boring so we are left with different means to measure the distance between points on the spacetime "grid"
 - Minkowski
 - Schwarzschild - static and stationary
 - Kerr - just stationary
 - Fully dynamic Spacetimes - neither static nor stationary
 - Others do exist but they pertain more to cosmology than surrounding individual massive bodies
- Minkowski is used when the massive body has no real effect on the spacetime itself, the masses are too small, or too far away.
- Schwarzschild, first let us consider a cow, next we assume it is a sphere...
- Kerr, let us take that cow and assume it is elliptical... then make it spin?
- Fully dynamic spacetimes are complicated and would need to be considered if the accretion mass was sufficient to significantly modify the mass of the accretor.

Kerr

- Since more "realistic" systems are expected to at a minimum have angular momentum, we use the Kerr metric
- The Kerr metric requires the following assumptions
 - Accretion rate is insufficient to modify the spacetime considerably
 - The massive bodies are axisymmetric
 - The massive bodies in space are rotating
- Important features of Kerr
 - Maximum angular momentum, J , is equal to the mass M (geometric units)
 - Has an event horizon
 - Has an ergosphere

Vorticity and Helicity

- Vorticity, ω

- Newtonian: $\vec{\omega} = \nabla \times \vec{v}$
- Relativistic: $\omega^\mu = \frac{1}{\sqrt{-g}} \epsilon^{\mu\nu\lambda\eta} u_{\lambda;\eta} u_\nu$

Using analogies between fluid dynamics and magnetodynamics we find the magnetic field can be treated in a similar way

- Newtonian: $\vec{B} = \nabla \times \vec{A}$
- Relativistic: $B^\mu = \frac{1}{\sqrt{-g}} \epsilon^{\mu\nu\lambda\eta} A_{\lambda;\eta} A_\nu$

- Helicity

- $H = \int_V \omega^\mu u_\mu$ - Helicity
 - $H_m = \int_V A^\mu B_\mu$ - Magnetic Helicity
 - $H_c = \int_V B^\mu \omega_\mu$ - Cross Helicity
- Helicity is regarded as a constant of motion, thus in numerical codes, these can be monitored for the validity of the solution.

Waves

- Characteristic velocities

- Magnetohydrodynamics involves three type of characteristic velocities
 - Alfvén Velocity
 - Fast Magnetosonic Velocity
 - Slow Magnetosonic Velocity
- Alfvén velocity comes from the magnetic field wave equation
- The Fast and slow magnetosonic velocities come from the velocity wave equation
- Fast waves have characteristic velocities greater than the Alfvén velocity
- Slow waves have characteristic velocities less than the Alfvén velocity
- Relativistically these must be solved numerically

Real Parameters

- For real accretion disks I will have to attempt to setup the initial conditions as seen from astronomical data
- For these systems we expect the following:
 - $Re > 10^4$
 - $R_M \sim 10^{10}$ (Solar Corona)
 - $\rho_o \sim 10^{-5} - 10^{32} cm^{-3}$
 - $|B| \sim 10^{-12} - 10^{20} G$
 - $\beta \sim 10^{-5} - 10^{20}$
- these ranges include the Newtonian as well as relativistic cases

Typical Setup

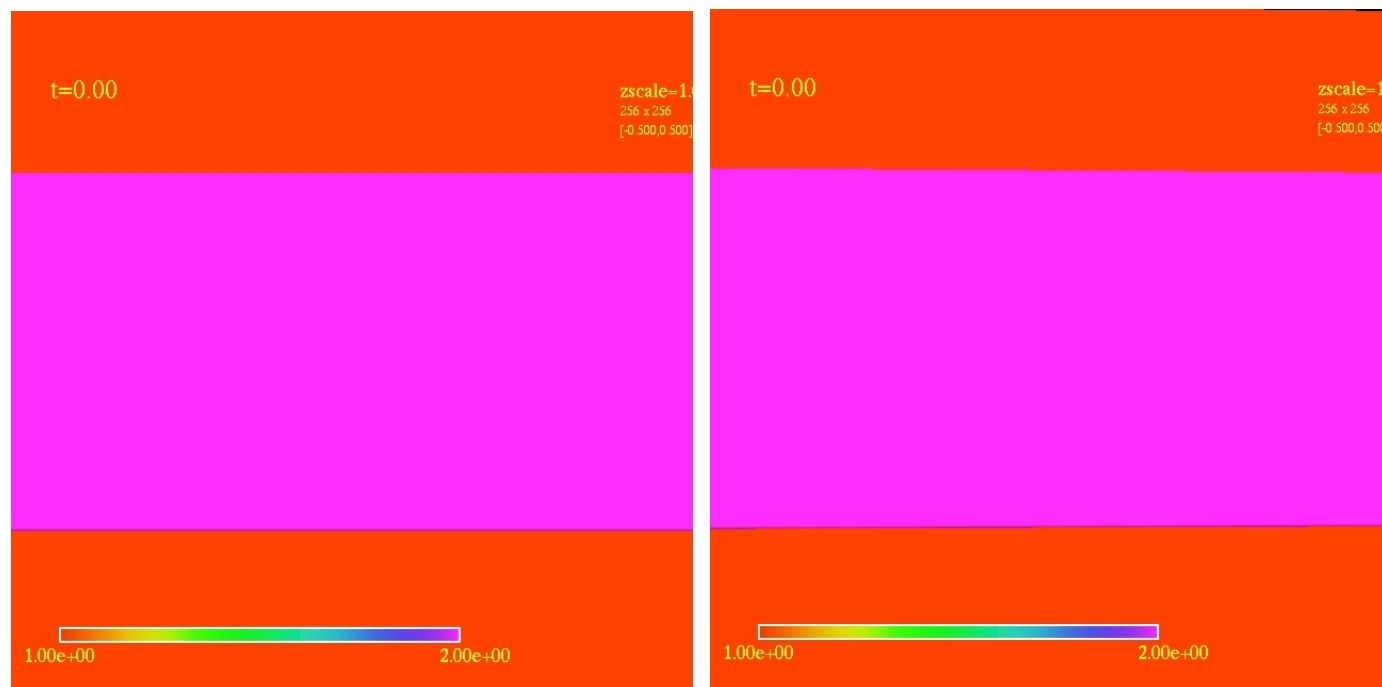
- So for my research the typical parameters for an accretion disk are
 - Radius $\rightarrow 0.26a - 0.3a$
 - Accretion rate $\rightarrow 10^{-4}M_{\odot}/y$
 - Average flow rate $\rightarrow 2.3E5 - 6.0E5 \text{ m/s}$
 - Average pressure $\rightarrow 10^{-10}Pa$
 - Average density $\rightarrow 10^{32}cm^{-3}$
 - Magnetic field strength $\rightarrow 10^{10} - 10^{15}G$
 - Magnetic field direction \rightarrow axisymmetric
 - Mass of accreting body $\rightarrow 3-10M_{\odot}$
 - Temperature $\rightarrow 10^4 - 10^8K$

Turbulence & Instabilities

- Instabilities and Turbulence
 - Instabilities arise when the system undergoes a small perturbation and the dispersion relation leads to complex frequencies, thus the amplitudes either expand uncontrollably.
 - Turbulence arises when energy differences in the system undergo a transition from one energy type to another. Typically this energy will cascade from one length scale to the next, until viscous terms become non-negligible
 - There are a two types of turbulence that are of immediate concern in magnetohydrodynamic systems
 - Kelvin Helmholtz Instability
 - Magnetorotational Instability

Preliminary Results - Minkowski spacetime

- In the Minkowski spacetime I have implemented the Kelvin-Helmholtz instability
- The Kelvin-Helmholtz instability comes from the over abundance of kinetic energy in a localized region. This physically comes from differential rotation which is expected to be found in accretion disks
- There is slipping between the two layers of the fluid. Relative velocity between the two streams is $0.8c$.

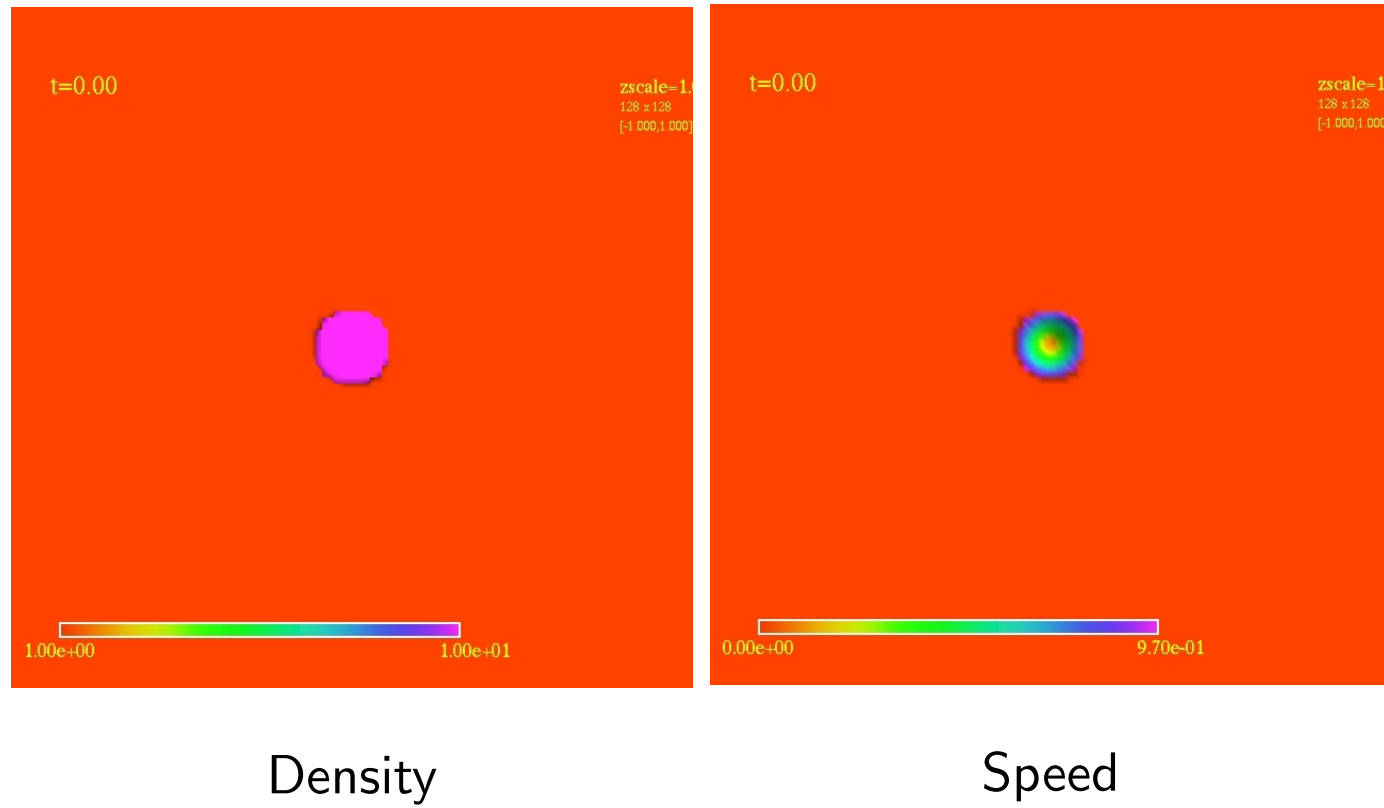


KHI No Magnetic field.

KHI With Magnetic Field,
 $B_x = 0.5$

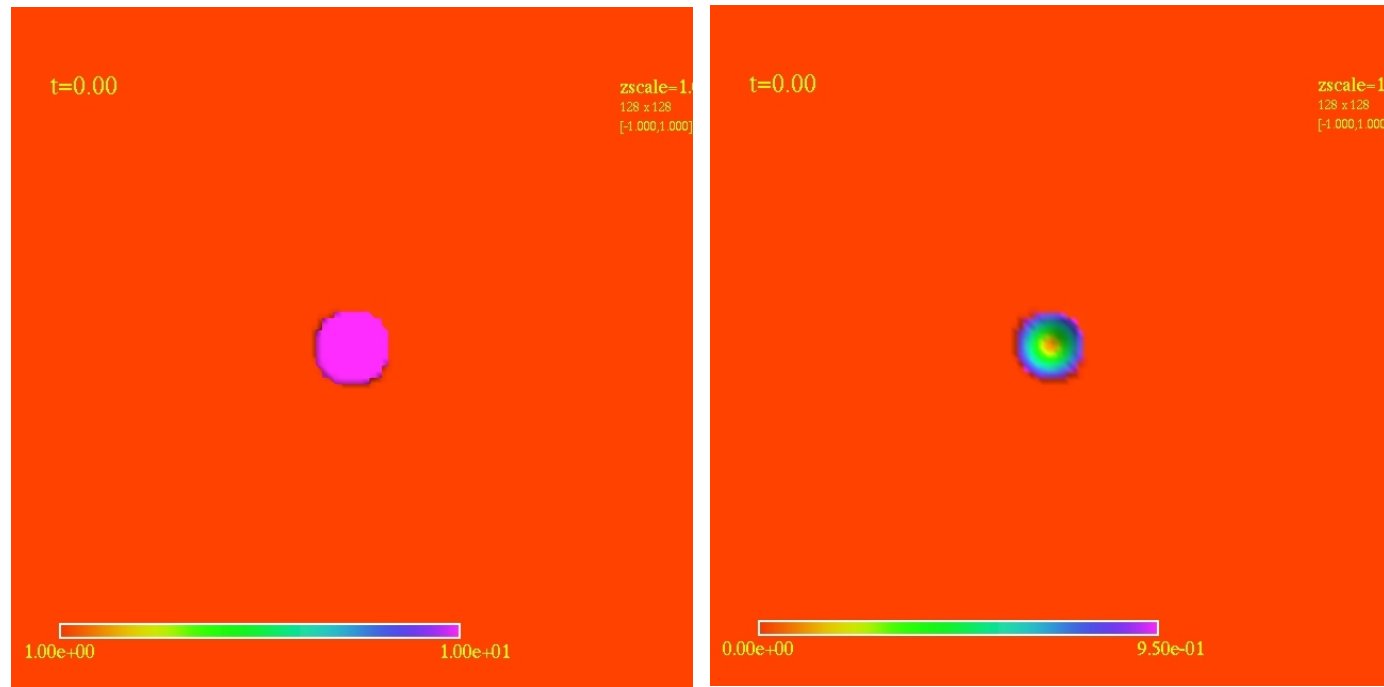
Preliminary Results - Minkowski spacetime

- In the Minkowski spacetime I have implemented a rotor, edge angular velocity $\Omega = 9.75$
- Pressure = 1.0
- Density = 10 inside the disk, 1 outside of the disk



Preliminary Results - Minkowski spacetime

- Now including the magnetic field, $B_x = 0.5$
- Pressure = 1.0
- Density = 10 inside the disk, 1 outside of the disk



Density

Speed

Current Research

- Magnetorotational Instability
 - Rotational energy is converted to magnetic energy
 - Thought to underlie viscous dissipation when matter falls onto the compact object from a companion
 - This could answer the angular momentum transport problem
 - Infalling matter has considerable angular momentum
 - This forms the rotating disk around the object, with differential rotation
 - Inner regions lose angular momentum due to viscosity and fall inward, outer regions gain angular momentum and move outward
 - infalling matter perturbs the outer regions preventing the outflow

Current Project - Numerical Magnetohydrodynamics

- Motivation

- Existing theories and codes appear to work well, however they all rely on an ideal equation of state, other equations of state may lead to results that come closer to the observed phenomenon.
- More realistic systems also consist of more than one fluid type, however this is beyond the scope of my project
- To study the turbulence in accretion disks
- To study an expansion to the thin disk approximation to accretion flows
- Ultimately, to better understand the complex dynamics of accretion disks around compact objects such as black holes

Current Project - Numerical Magnetohydrodynamics

- Questions to consider
 - How does a more realistic EoS impact the turbulence in MRI?
 - Will this realistic EoS allow for angular momentum transport in the accretion disk?
 - Does turbulence aid in the angular momentum transport by dissipating the energy to smaller scales?
 - What happens if matter infalls as lumps (high density regions) rather than as a steady stream of thin matter?
 - What are the effects of frame dragging for infalling matter to an observer at infinity (earth).

Physical Setup

- The next setup
 - Kerr parameter $a = 0, 0.5, 1$
 - Mass $M = 1$ - scaled
 - Equatorial plane
 - Inside the disk
 - $\vec{v} = \vec{0}$
 - $\vec{B} = (B_r, 0, 0)$
 - $P = \text{low}$
 - $\rho = \text{low}$
 - Periodic BC's at $\phi = 0, \pi/2$
 - Outflow at the event horizon $R_{EH} = M + \sqrt{M^2 - a^2}$ (inner radius)
 - Outflow at outer radius $\sim 6R_{EH}$, except at a single point
 - Single Point
 - $\vec{v} = (v_r, v_\phi, 0)$
 - $\vec{B} = (B_r, 0, 0)$
 - $P = \text{high}$
 - $\rho = \text{high and steady}$

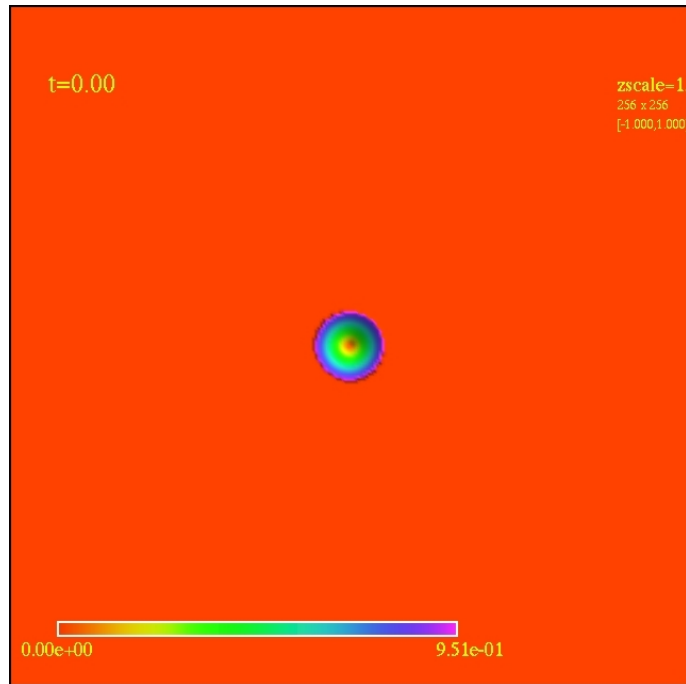
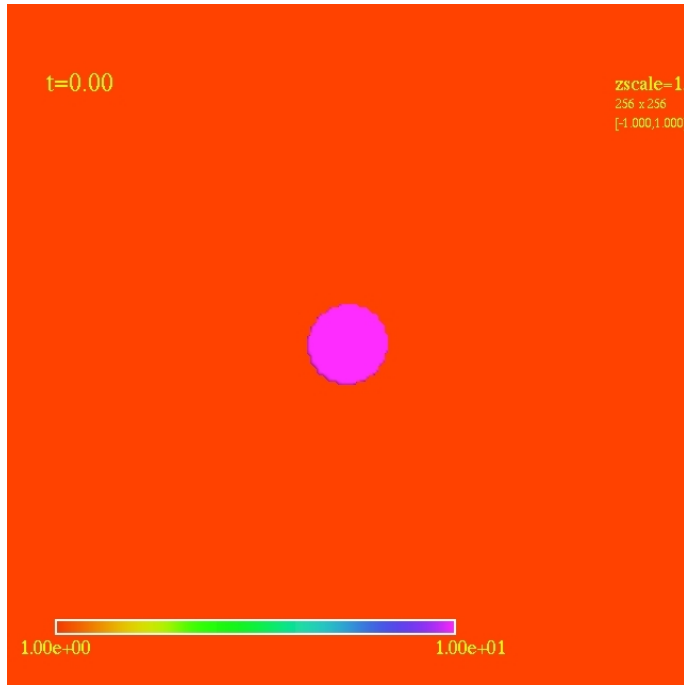
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 - Single Point
 - $\vec{v} = (v_r, v_\phi, 0)$
 - $\vec{B} = (B_r, 0, 0)$
 - $P = \text{high}$
 - $\rho = \text{high}$ and a function of time, periodic or possibly random

C'est Fin

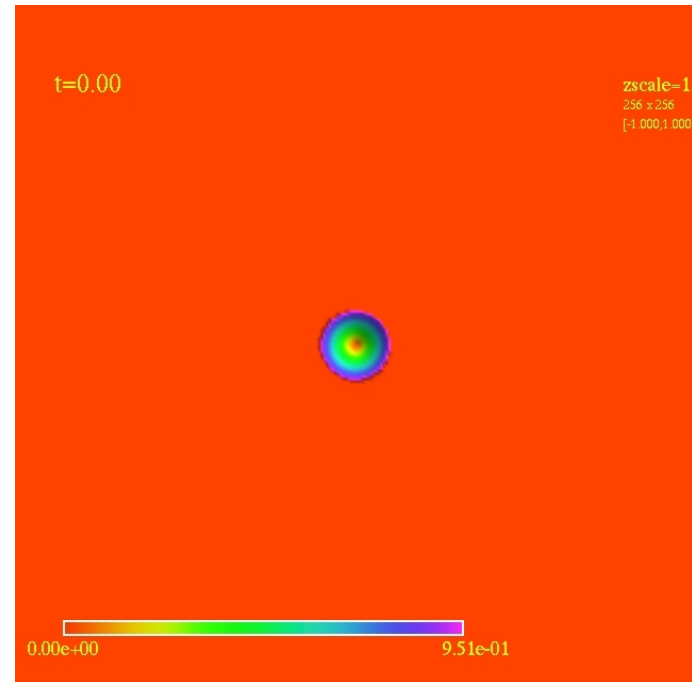
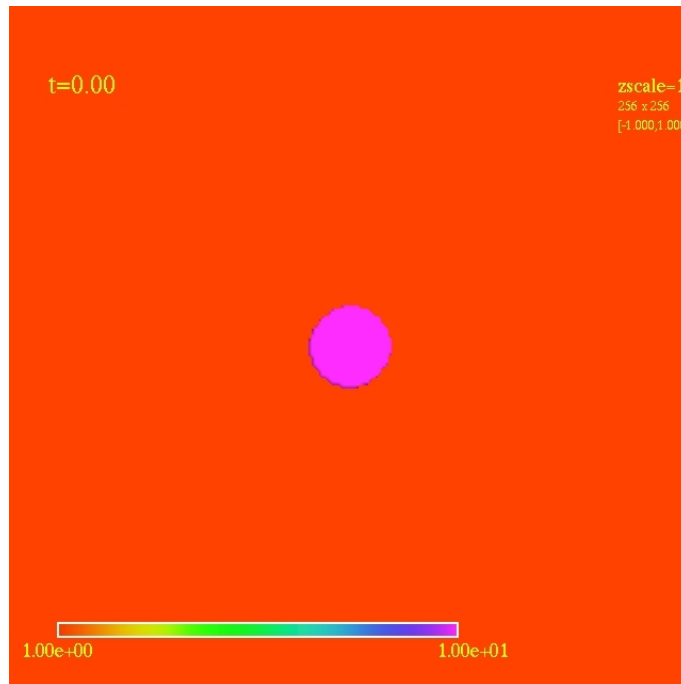
- Questions?

More Preliminary Results - Minkowski spacetime



Preliminary Results - Minkowski spacetime

- Now including the magnetic field



The Solver

- The Roe Solver

$$\frac{\partial q}{\partial t} + \frac{\partial f(q)}{\partial x} = \Sigma(q)$$

Cell average:

$$Q_i \approx \frac{1}{\Delta V} \int_{\Delta V} q dV$$

Integrate conservative equation over a small volume, and divide by that same volume

$$\frac{1}{\Delta V} \int_{\Delta V} \frac{\partial}{\partial t} q dx + \frac{1}{\Delta V} \int_{\Delta V} \frac{\partial}{\partial x} f(q) dV = \frac{1}{\Delta V} \int_{\Delta V} \Sigma(q) dV$$

The Solver

which can be re-arranged, using Stokes' theorem

$$\frac{1}{\Delta V} \frac{\partial}{\partial t} \int_{\Delta V} q dx + \frac{1}{\Delta V} \int_{\partial V} f(q) dS = \frac{1}{\Delta V} \int_{\Delta V} \Sigma(q) dV$$

So now using our cell average, and the mean value theorem on the source term we get

$$\frac{\partial}{\partial t}(Q_i) + \frac{1}{\Delta V} \left(f_{i+\frac{1}{2}} - f_{i-\frac{1}{2}} \right) = \Sigma(Q_i)$$

finite difference the time derivative

$$(Q_i)^{n+1} = (Q_i)^n - \frac{\Delta t}{\Delta V} \left(f_{i+\frac{1}{2}} - f_{i-\frac{1}{2}} \right) + \Delta t \Sigma_i$$

Flux Approximations

- Shock Capturing

We think of the discretization Q_i^n as being a piecewise constant reconstruction of the solution $q(x)$. Then at every cell boundary we have a Riemann problem (the discontinuity). To estimate the flux in the above equation we write the flux as $f(q^*)$ where q^* is the solution at the cell boundary to the problem given by:

$$\frac{\partial q}{\partial t} + A \frac{\partial q}{\partial x} = 0$$

with the Jacobian $A = \partial F / \partial q$ is constant.

For $x = 0$: If $A > 0$ the flow is to the right, so $q^* = q_L$, this corresponds to $f(q^*) = Aq_L$. If $A < 0$ the flow is to the left, so $q^* = q_R$, which corresponds to $f(q^*) = Aq_R$. Rather than using an if/then approach we use a general form:

$$f_{i+1/2} = f(q_{i+1/2}^*) = \frac{1}{2} (Aq_L + Aq_R - |A|(q_R - q_L))$$

So if $A > 0$ then $f = \frac{1}{2}(Aq_L + Aq_L) = Aq_L$