

**PHYS 410   Finite Difference Methods   Oct 19, 2000**  
**Expected Behaviour of Finite-Difference Approximations**  
**(Convergence and Accuracy)**

We have already seen that the basic “control parameter” of a typical FDA (finite-difference approximation) is the mesh-spacing,  $h$ . Fundamentally, for sensibly constructed FDA’s, we expect the error in the approximation to go to 0 as  $h$  goes to 0.

**Notation and Definitions**

Let

$$L u = f \tag{1}$$

denote a general *differential* system. For simplicity and concreteness, you can think of  $u = u(x)$  as a single function of one variable, but the following discussion also applies to cases in multiple independent variables ( $u(x, t), u(x, y, t), \dots$  etc.), as well as multiple *dependent* variables ( $u = \mathbf{u} = [u_1, u_2, \dots, u_n]$ ).

In (1),  $L$  is some differential operator ( $L = d^2/dx^2$  in the BVP example we’ve studied previously), and  $f$  is some specified function. We will generically denote an FDA of (1) by

$$\hat{L} \hat{u} = \hat{f} \tag{2}$$

where  $\hat{u}$  is the discrete solution,  $\hat{f}$  is the specified function evaluated on the finite-difference mesh, and  $\hat{L}$  is the finite-difference approximation to  $L$ .

**Truncation Error:** The truncation error,  $\hat{\tau}$ , of an FDA is defined by

$$\hat{\tau} \equiv \hat{L} u - \hat{f} \tag{3}$$

where  $u$  satisfies the continuum system (1). We note that the *form* of the truncation error can always be computed (typically using Taylor series expansions) from the finite difference approximation and the differential equations—we will see an example shortly.

**Order of a Finite-Difference Approximation:** Assuming that the FDA is characterized by a *single* discretization scale,  $h$ , we say that the FDA is *p-th order accurate* or simply *p-th order* if

$$\lim_{h \rightarrow 0} \hat{\tau} = O(h^p) \quad \text{for some integer } p \tag{4}$$

**Solution Error:** The solution error,  $\hat{e}$ , associated with an FDA is defined by

$$\hat{e} \equiv u - \hat{u} \tag{5}$$

**Relation Between Truncation Error and Solution Error**

It is common to tacitly assume that

$$\hat{\tau} = O(h^p) \quad \text{implies} \quad \hat{e} = O(h^p)$$

This assumption is often warranted but it is extremely instructive to consider *why* it is warranted and to investigate in some detail the *nature* of the solution error,  $\hat{e}$ , for a simple yet representative example.

### Example

Consider one of the simplest possible differential systems:

$$L u(x) \equiv \left( \frac{d}{dx} - 1 \right) u(x) = 0 \quad \text{on } 0 \leq x \leq 1 \quad \text{with } u(0) = 1 \quad (6)$$

Clearly, the unique solution of this DE is

$$u(x) = e^x.$$

We introduce a uniform finite-difference mesh,  $x_j$ ,

$$x_j = jh, \quad j = 0, 1, \dots, n-1 \quad \text{where } h = \frac{1}{n-1}$$

and consider the following difference operators:

$$\Delta_+^x u_j \equiv h^{-1} (u_{j+1} - u_j) \quad (7)$$

$$\mu_+^x u_j \equiv \frac{1}{2} (u_{j+1} + u_j) \quad (8)$$

Now consider Taylor series expansions of  $u_j$  and  $u_{j+1}$  about

$$u_{j+\frac{1}{2}} \equiv u(x_{j+\frac{1}{2}}) \equiv u \left( \frac{1}{2} (x_j + x_{j+1}) \right) \equiv \bar{u}$$

We have

$$u_{j+1} = \bar{u} + \left( \frac{1}{2}h \right) \bar{u}' + \frac{1}{2} \left( \frac{1}{2}h \right)^2 \bar{u}'' + \frac{1}{6} \left( \frac{1}{2}h \right)^3 \bar{u}''' + \frac{1}{24} \left( \frac{1}{2}h \right)^4 \bar{u}'''' + O(h^5)$$

$$u_j = \bar{u} - \left( \frac{1}{2}h \right) \bar{u}' + \frac{1}{2} \left( \frac{1}{2}h \right)^2 \bar{u}'' - \frac{1}{6} \left( \frac{1}{2}h \right)^3 \bar{u}''' + \frac{1}{24} \left( \frac{1}{2}h \right)^4 \bar{u}'''' + O(h^5)$$

so

$$\Delta_+^x u_j \equiv h^{-1} (u_{j+1} - u_j) = \bar{u}' + \frac{1}{24} h^2 \bar{u}''' + O(h^4) \quad (9)$$

$$\mu_+^x u_j \equiv \frac{1}{2} (u_{j+1} + u_j) = \bar{u} + \frac{1}{8} h^2 \bar{u}'' + O(h^4) \quad (10)$$

Thus, we can identify the *difference operators*,  $\Delta_+^x$  and  $\mu_+^x$ , with (formal) power series (in  $h$ ) of *differential operators*:

$$\Delta_+^x \equiv \frac{d}{dx} + \frac{1}{24} h^2 \frac{d^3}{dx^3} + O(h^4) \quad (11)$$

$$\mu_+^x \equiv 1 + \frac{1}{8} h^2 \frac{d^2}{dx^2} + O(h^4) \quad (12)$$

We now write down our FDA of (6):

$$\left( \frac{d}{dx} - 1 \right) u(x) = 0 \quad \longrightarrow \quad (\Delta_+^x - \mu_+^x) u_j = 0 \quad (13)$$

(i.e.  $\hat{L} = \Delta_+^x - \mu_+^x$ ). Explicitly, we have

$$\frac{u_{j+1} - u_j}{h} = \frac{u_{j+1} + u_j}{2} \quad j = 0, 1, \dots, n-2 \quad \text{with } u_0 = u(0) = 1 \quad (14)$$

Let us first consider the *truncation error* associated with (13,14):

$$\begin{aligned} \hat{\tau} \equiv \hat{L}u - \hat{f} &= \hat{L}u = (\Delta_+^x - \mu_+^x) u \\ &= \left( \frac{d}{dx} + \frac{1}{24}h^2 \frac{d^3}{dx^3} - 1 - \frac{1}{8}h^2 \frac{d^2}{dx^2} + O(h^4) \right) \bar{u} \\ &= \left( \frac{d}{dx} - 1 \right) \bar{u} + h^2 \left( \frac{1}{24} \frac{d^3}{dx^3} - \frac{1}{8} \frac{d^2}{dx^2} \right) \bar{u} + O(h^4) = O(h^2) \end{aligned}$$

where we have used the original differential equation (6) in the form

$$\left( \frac{d}{dx} - 1 \right) \bar{u} = 0.$$

Thus, since  $\hat{\tau} = O(h^2)$ , our FDA is *second order*. Note, however, that we had to be careful about choosing the  $x$  value about which we performed our Taylor series expansions—in general we must choose the expansion point which gives the *highest-order* truncation error or, intuitively, the point about which the scheme is naturally “centred”.

The FDA (14) is sufficiently simple (and linear) that we can solve it explicitly:

$$\frac{u_{j+1} - u_j}{h} = \frac{u_{j+1} + u_j}{2} \quad \rightarrow \quad u_{j+1} = \left( \frac{h^{-1} + \frac{1}{2}}{h^{-1} - \frac{1}{2}} \right) u_j = \left( \frac{1 + \frac{h}{2}}{1 - \frac{h}{2}} \right) u_j \equiv \rho u_j \quad \text{where } \rho \equiv \frac{1 + \frac{h}{2}}{1 - \frac{h}{2}}$$

Thus we have

$$u_j = \rho^j u_0 = \rho^j \quad (15)$$

where  $\rho^j$  denotes the  $j$ -th power of  $\rho$  and we have used the initial condition  $u_0 = 1$ . Now, we can write  $\rho^j$  as follows:

$$\rho^j = \exp(j \ln \rho) = \exp \left( j \left( \ln \left( 1 + \frac{h}{2} \right) - \ln \left( 1 - \frac{h}{2} \right) \right) \right).$$

Then, using the Taylor series expansion

$$\ln(1+x) = x - \frac{1}{2}x^2 + \frac{1}{3}x^3 + O(x^4)$$

we have

$$\ln \left( 1 + \frac{h}{2} \right) - \ln \left( 1 - \frac{h}{2} \right) = h + \frac{1}{12}h^3 + O(h^5)$$

so that

$$\begin{aligned} \rho^j &= \exp \left( jh + (jh) \frac{1}{12}h^2 + O(h^4) \right) = \exp(jh) \exp \left( jh \frac{h^2}{12} + O(h^4) \right) = e^{x_j} \left( 1 + \frac{h^2}{12} x_j + O(h^4) \right) \\ &= e^{x_j} + \frac{1}{12}h^2 x_j e^{x_j} + O(h^4) \end{aligned}$$

Thus, the *solution error*,  $\hat{e}$  is given by

$$\hat{e} = u - \hat{u} = -\frac{1}{12}h^2 x e^x + O(h^4) = O(h^2) \quad (16)$$

Note in particular, the *form* of the solution error; to leading order it is

$$h^2 \times -\frac{1}{12}x e^x = -h^2 \times e_2(x)$$

where  $e_2(x)$  is a *function* ( $\frac{1}{12}x e^x$ ) with smoothness (i.e. magnitude of derivatives) comparable to the continuum solution,  $u(x) = e^x$ .

There is another way to derive (16) which clearly illustrates the fundamental lesson concerning the errors in finite difference approximations.

Let us *assume* that  $u$  and  $\hat{u}$  are related by the asymptotic ( $h \rightarrow 0$ ) expansion,

$$\hat{u} = u + h^2 e_2 + h^4 e_4 + \dots \quad (17)$$

which we call a *Richardson expansion* (after L.F. Richardson, who studied such matters in the early part of this century).

We start with the FDA

$$\hat{L} \hat{u} = 0 \quad \longrightarrow \quad (\Delta_+^x - \mu_+^x) \hat{u} = 0$$

and replace both  $\hat{L}$  and  $\hat{u}$  by their “continuum expansions” (11,12,17):

$$\left( \frac{d}{dx} - 1 + h^2 \left( \frac{1}{24} \frac{d^3}{dx^3} - \frac{1}{8} \frac{d^2}{dx^2} \right) + O(h^4) \right) \left( u + h^2 e_2 + O(h^4) \right) = 0$$

We now demand that this equation vanish, *order by order*, in  $h$ . For the  $O(1)$  and  $O(h^2)$  cases we have

$$\begin{aligned} O(1) : \quad & \left( \frac{d}{dx} - 1 \right) u = 0 \quad \longrightarrow \quad u = e^x \quad (\text{consistency of FDA}) \\ O(h^2) : \quad & \left( \frac{d}{dx} - 1 \right) e_2 = \left( \frac{1}{8} \frac{d^2}{dx^2} - \frac{1}{24} \frac{d^3}{dx^3} \right) u \end{aligned}$$

Thus, we see that the error function,  $e_2$ , *itself* satisfies a differential equation which is very similar in form to the original DE. Moreover, given that we know  $u(x) = e^x$ , we can solve this DE for  $e_2$ . Specifically, we have

$$\left( \frac{d}{dx} - 1 \right) e_2 = \frac{1}{12} e^x \quad \longrightarrow \quad e_2 = \frac{1}{12} x e^x \quad (18)$$

and since our original *assumption* (17) was

$$\hat{u} = u + h^2 e_2 + O(h^4) = u + \frac{1}{12} h^2 x e^x + O(h^4)$$

we get

$$\hat{e} \equiv u - \hat{u} = -\frac{1}{12} h^2 x e^x + O(h^4)$$

as previously.

## Comments

Even in cases where we *don't* know the continuum solution (this clearly includes most of the interesting instances where we are likely to apply finite-difference techniques), it is still very useful to think of *difference operators* and *difference solutions* in terms of asymptotic expansions in powers of the mesh spacing,  $h$ :

$$\begin{aligned}\hat{L} &= L + h^2 L_2 + h^4 L_4 + O(h^6) \\ \hat{u} &= u + h^2 e_2 + h^4 e_4 + O(h^6)\end{aligned}$$

so that

$$\hat{L} \hat{u} = \hat{f}$$

actually represents an (infinite) hierarchy of differential systems

$$\begin{aligned}L u &= f \\ L e_2 &= -L_2 u \\ &\cdot \\ &\cdot \\ &\cdot\end{aligned}$$

In other words, in FDA's of continuum systems, the error is not "random"—rather, in principle, it is no less computable than the fundamental solution itself.