

PHYS 170 Section 101
Lecture 3
September 10, 2017

SEP 10—ANNOUNCEMENTS

- **Tutorials start tomorrow**
- **Mastering Engineering:**
 - Introductory assignment due Friday at 11:59 PM
 - First assignment due next Monday at 11:59 PM

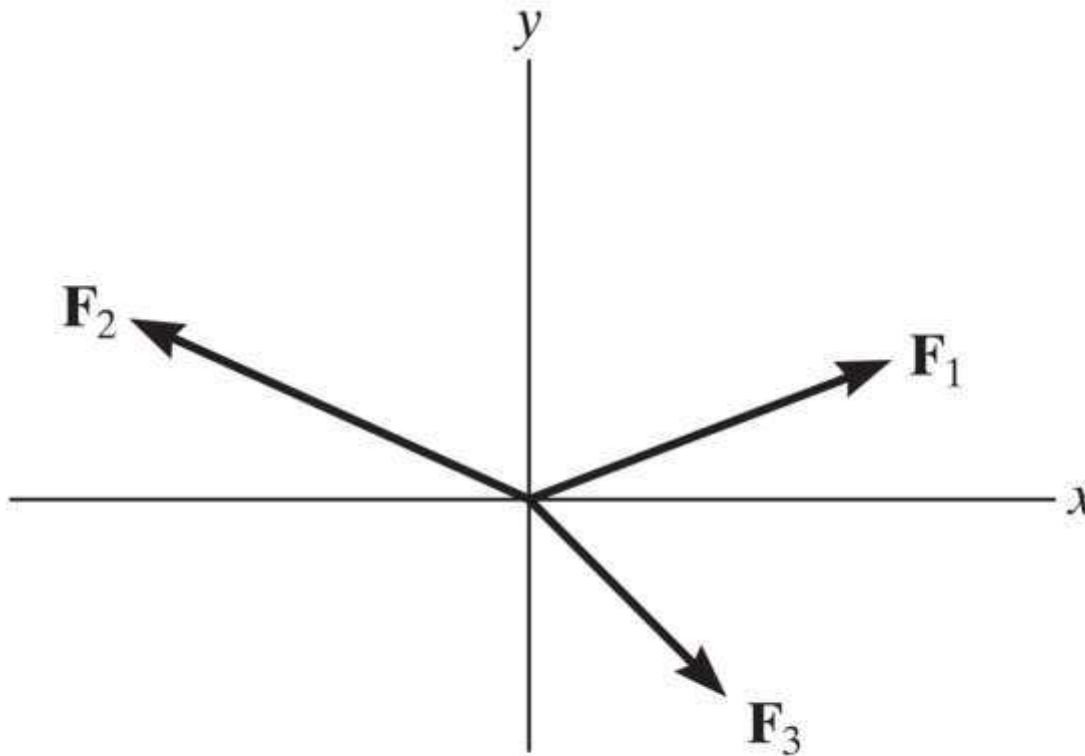
Lecture Outline/Learning Goals

- Sample problems: coplanar force systems
- Cartesian vectors (3 dimensions or 3D)
 - Right handed coordinate systems, rectangular components, unit vectors
 - Cartesian vector representation, magnitude of Cartesian vector
 - Cartesian vector: direction, coordinate direction angles, direction cosines
 - Addition and subtraction of Cartesian vectors

COPLANAR FORCE RESULTANTS

- We now wish to consider summing an arbitrary number of vectors in the xy plane. For example:

$$\mathbf{F}_R = \mathbf{F}_1 + \mathbf{F}_2 + \mathbf{F}_3$$



(a)

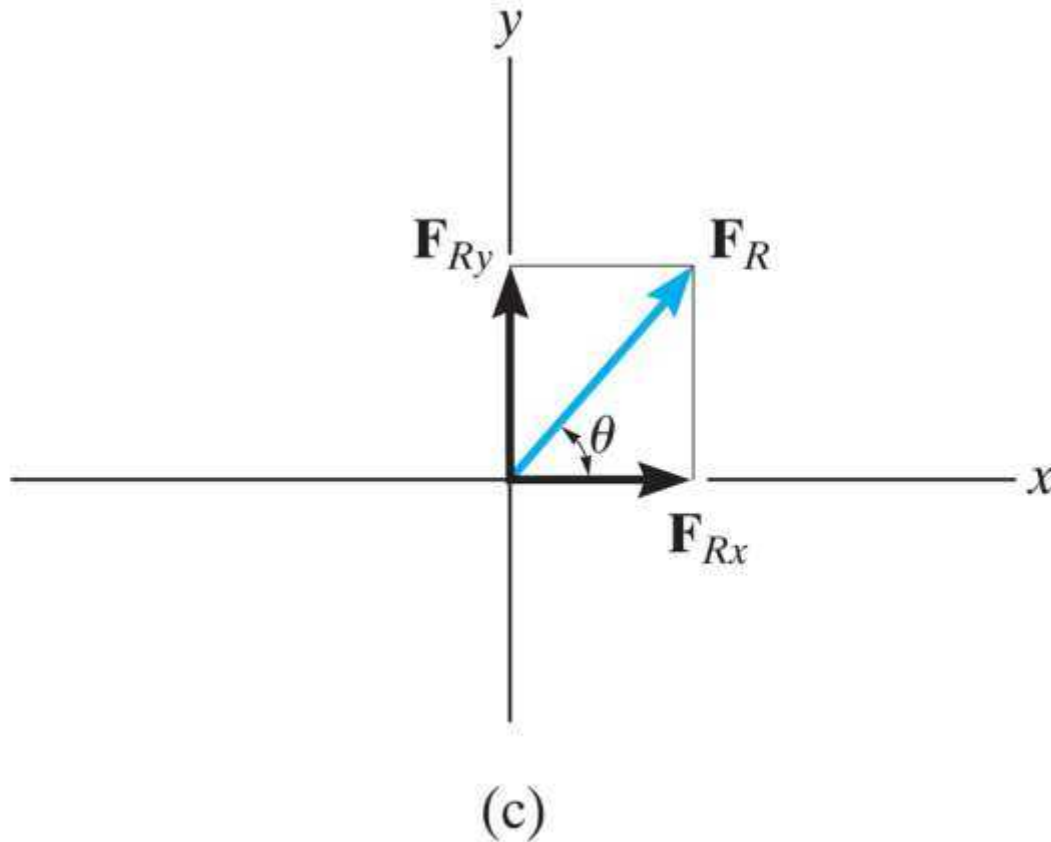
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- General case (arbitrary number of forces)

$$F_{Rx} = \sum F_x$$

$$F_{Ry} = \sum F_y$$

REPRESENTATION AS MAGNITUDE & DIRECTION



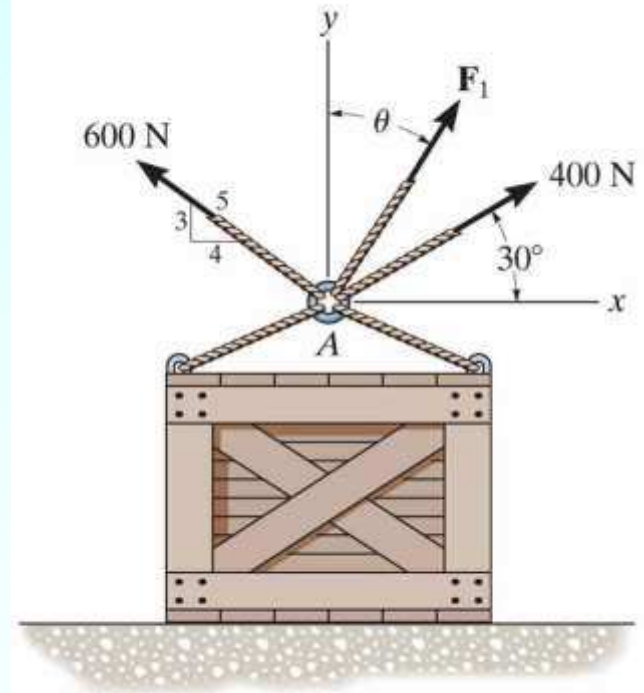
$$F_R = \sqrt{F_{Rx}^2 + F_{Ry}^2}$$

$$\theta = \tan^{-1} \left| \frac{F_{Ry}}{F_{Rx}} \right|$$

Problem 2-51 (page 41, 13th edition)

Determine the magnitude and direction measured counterclockwise from the positive x -axis of the resultant force of the three forces acting on the ring A .

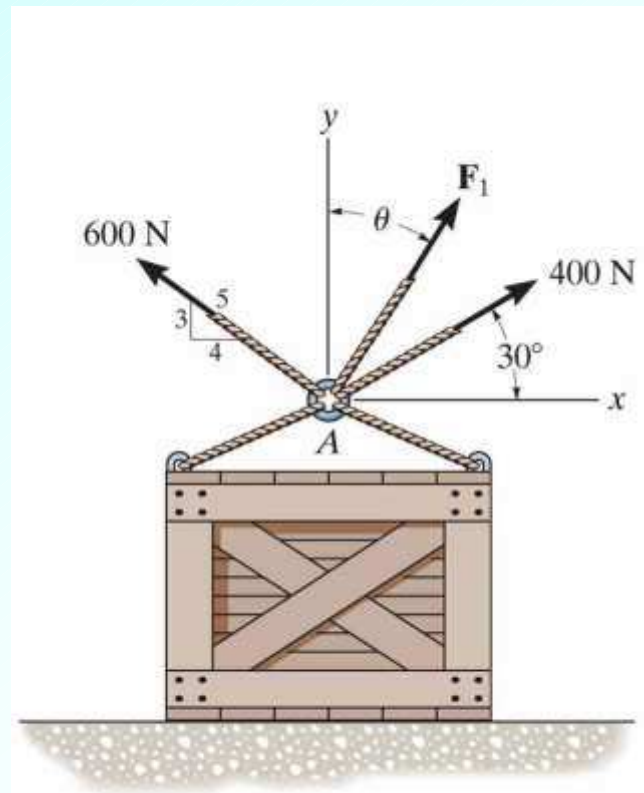
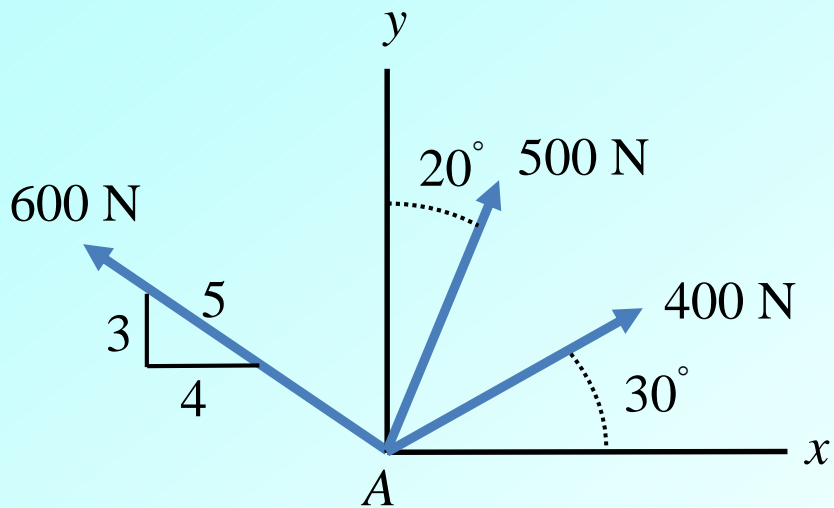
Take $F_1 = 500$ N and $\theta = 20^\circ$.



PROB02_039-040.jpg

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Problem 2-51 (page 41, 13th edition)



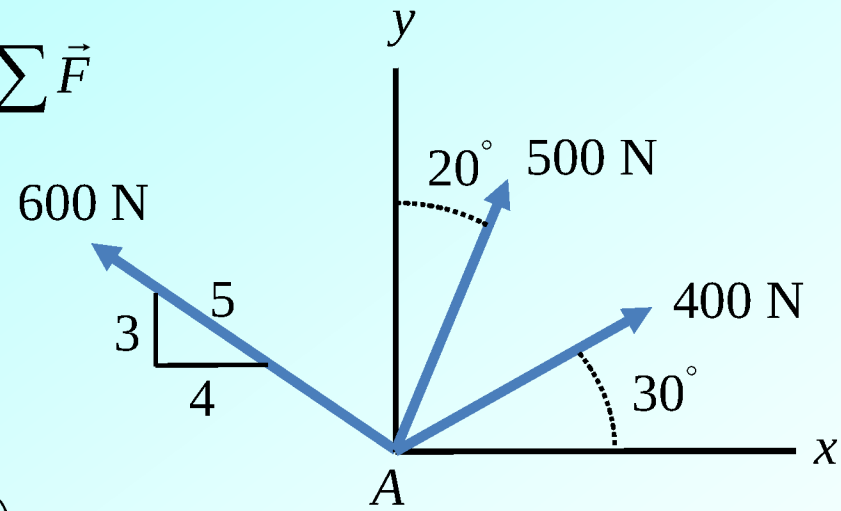
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Determine the magnitude and direction of $\vec{F}_R = \sum \vec{F}$

Cartesian Vector Method (suppressing units)

$$\vec{F}_R = F_{Rx} \vec{i} + F_{Ry} \vec{j} = F_R (\cos \phi \vec{i} + \sin \phi \vec{j})$$



$$F_{Rx} = \sum F_x = 400 \cos 30^\circ + 500 \sin 20^\circ - 600 \left(\frac{4}{5} \right) = 37.42 = A$$

Store in
calculator
memory "A"

$$F_{Ry} = \sum F_y = 400 \sin 30^\circ + 500 \cos 20^\circ + 600 \left(\frac{3}{5} \right) = 1030 = B$$

Store in
calculator
memory "B"

Answers

$$F_R = \sqrt{F_{Rx}^2 + F_{Ry}^2} = \sqrt{A^2 + B^2} = \mathbf{1.03 \text{ kN}}$$

Does this answer make sense?

$$\phi = \tan^{-1} (F_{Ry} / F_{Rx}) = \tan^{-1} (B / A) = \mathbf{87.9^\circ}$$

Problem 2-44 (page 41, 13th edition)

The magnitude of the resultant force acting on the bracket is 400 N.

Determine the magnitude of \vec{F}_1 . Take $\phi = 30^\circ$. Disregard the u axis.

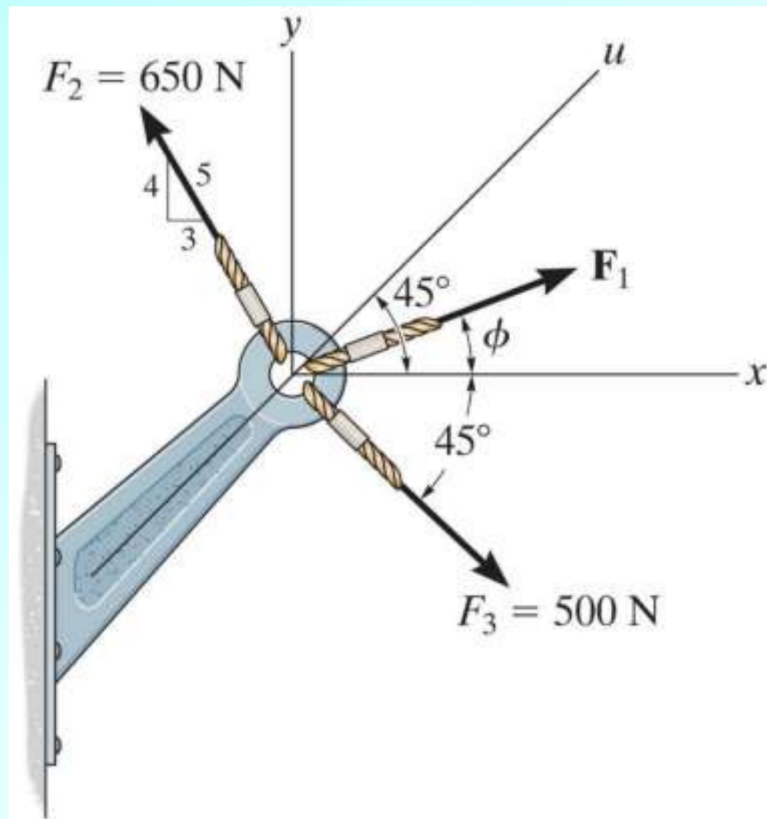


Figure: 02_P044-045-046

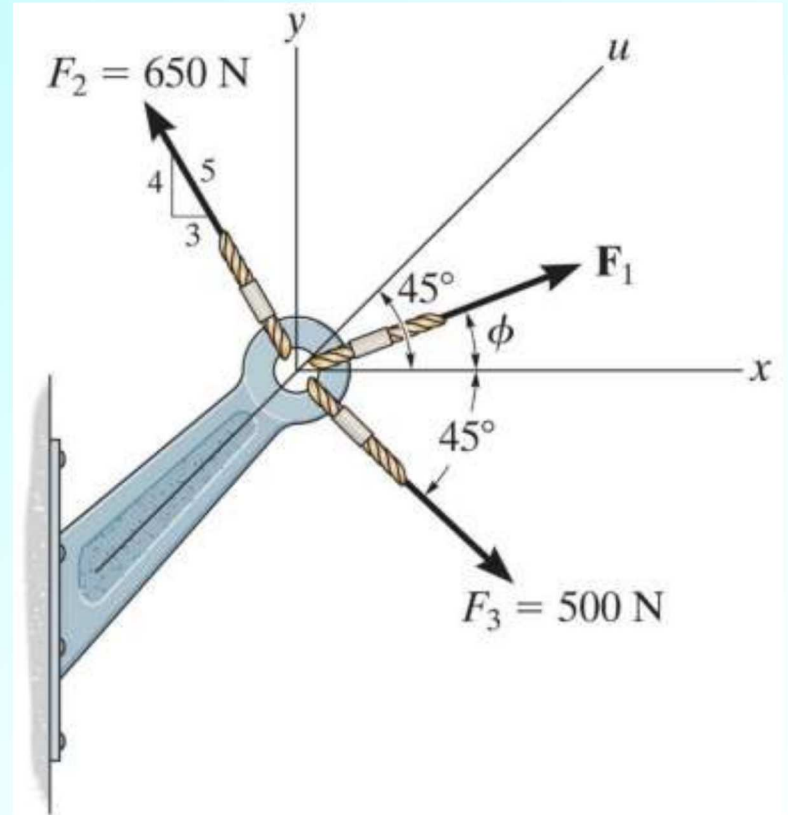
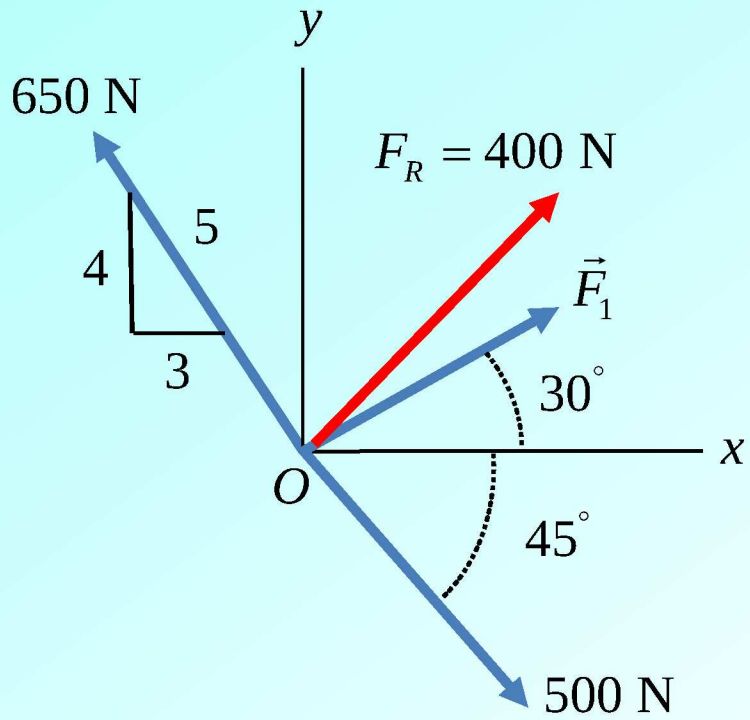


Figure: 02_P044-045-046

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- Determine F_1 so that $F_R = 400$ N: $\vec{F}_R = \sum \vec{F}$
- Cartesian Vector Method** (suppressing units)

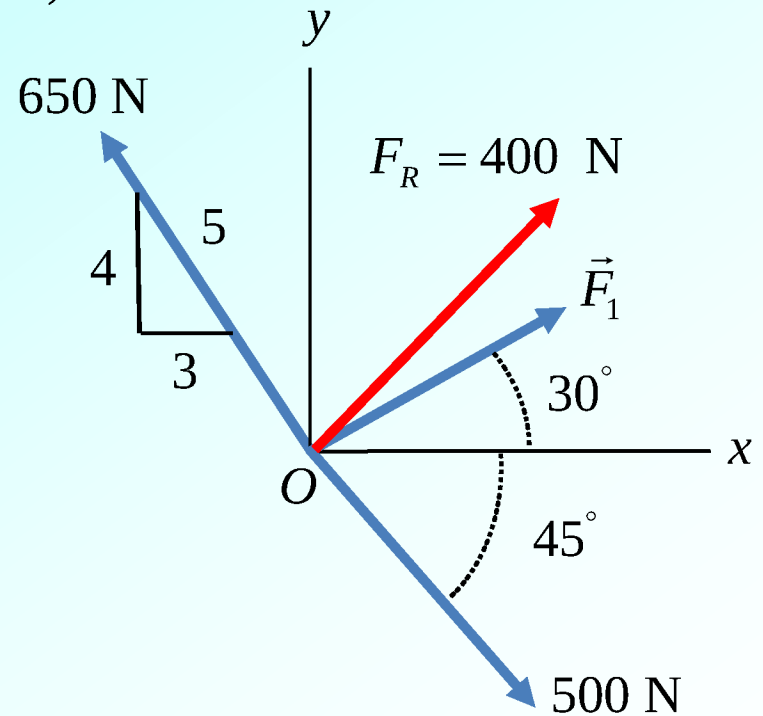
$$\vec{F}_R = F_{Rx} \vec{i} + F_{Ry} \vec{j}$$

$$F_{Rx} = \sum F_x = -650 \left(\frac{3}{5} \right) + F_1 \cos 30^\circ + 500 \cos 45^\circ$$

$$F_{Ry} = \sum F_y = 650 \left(\frac{4}{5} \right) + F_1 \sin 30^\circ - 500 \sin 45^\circ$$

$$F_R = \sqrt{F_{Rx}^2 + F_{Ry}^2}$$

$$400 = \sqrt{\left(-390 + F_1 \cos 30^\circ + 500 \cos 45^\circ \right)^2 + \left(520 + F_1 \sin 30^\circ - 500 \sin 45^\circ \right)^2}$$



$$400 = \sqrt{\left(-390 + F_1 \cos 30^\circ + 500 \cos 45^\circ\right)^2 + \left(520 + F_1 \sin 30^\circ - 500 \sin 45^\circ\right)^2}$$

- This is a nonlinear equation in the single unknown F_1 which we could solve by squaring both sides and solving the resulting quadratic equation (**leave as an exercise**)
- Alternatively, we can use the **solver** function on a TI graphing calculator to get

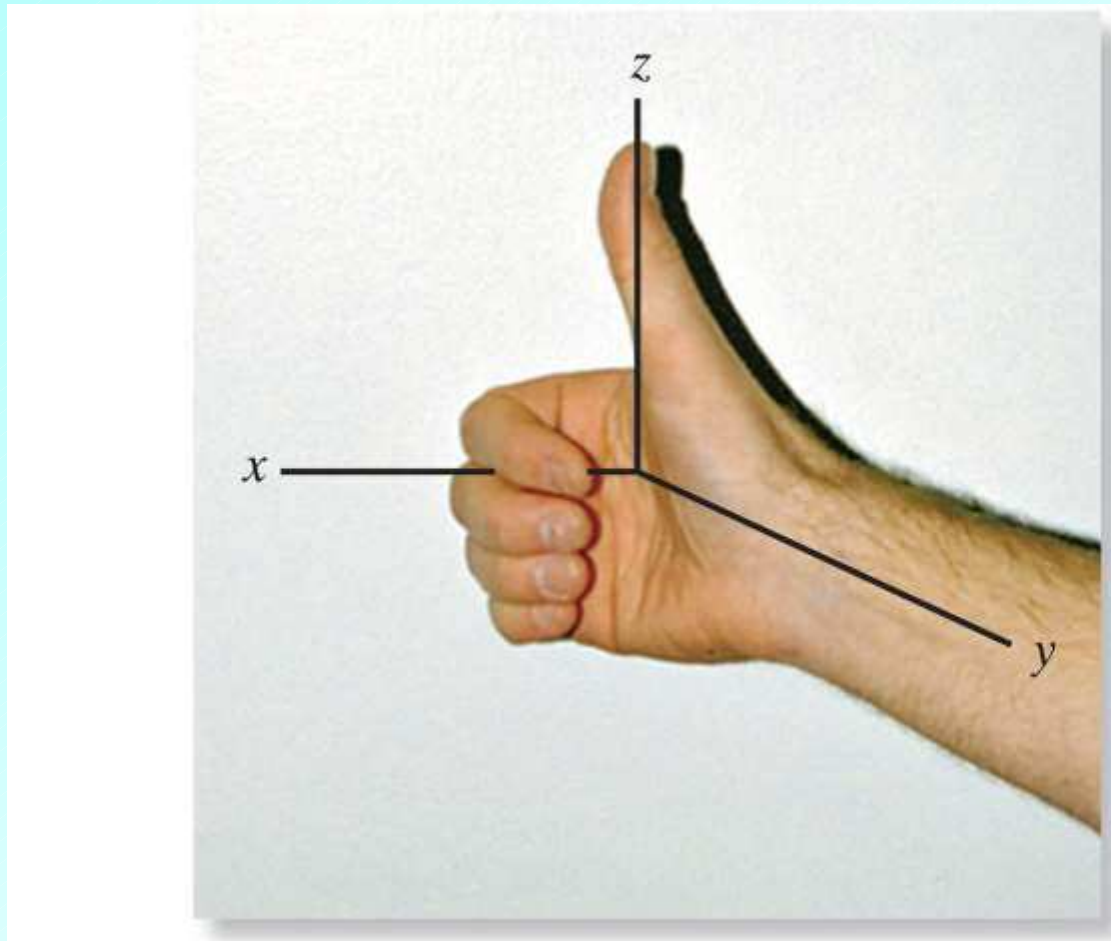
$$F_1 = 314 \text{ N} \quad \text{or} \quad F_1 = -417 \text{ N}$$

- Note that the negative sign tells us that for that answer \vec{F}_1 must be in the direction opposite to that shown in the figure. Also, to get the two distinct roots from **solver**, I used a large positive number as a guess in the first instance (1000), and a large (in magnitude) negative number in the second (-1000)

2.5-2.6: CARTESIAN VECTORS (3 DIMENSIONS or 3D)

- TRICKY TO MASTER FOR MANY STUDENTS
- **PRACTICE WILL HELP!!**
- Work through examples/problems in text, and additional problems online (Canvas)
- Discussion applies to vectors in general, but will have specific application of **force vectors** in mind

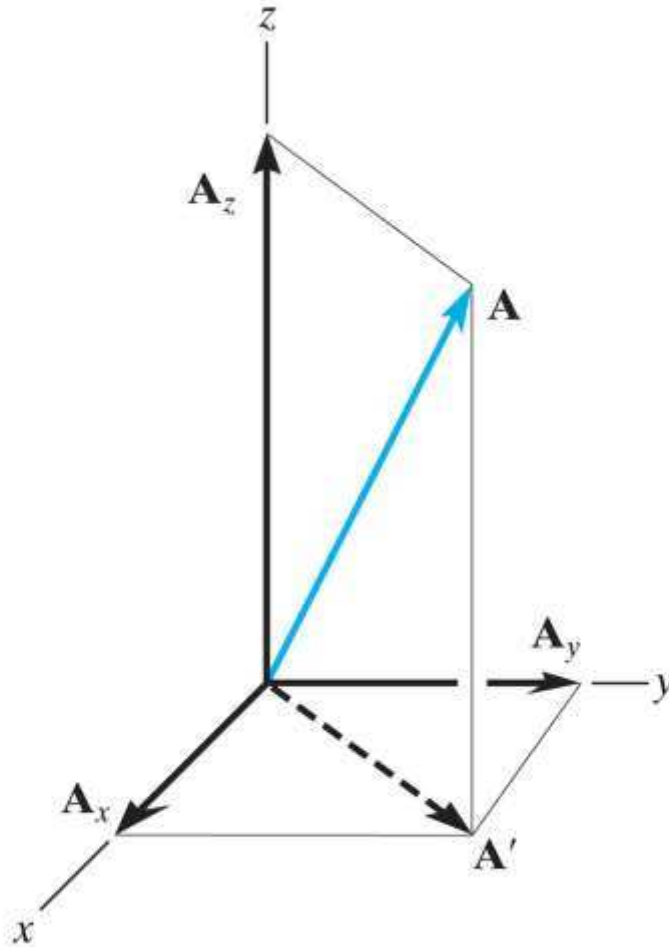
RIGHT HANDED COORDINATE SYSTEM



“Squeeze” (rotate) x axis into y axis with fingers of right hand—thumb then points in direction of z axis

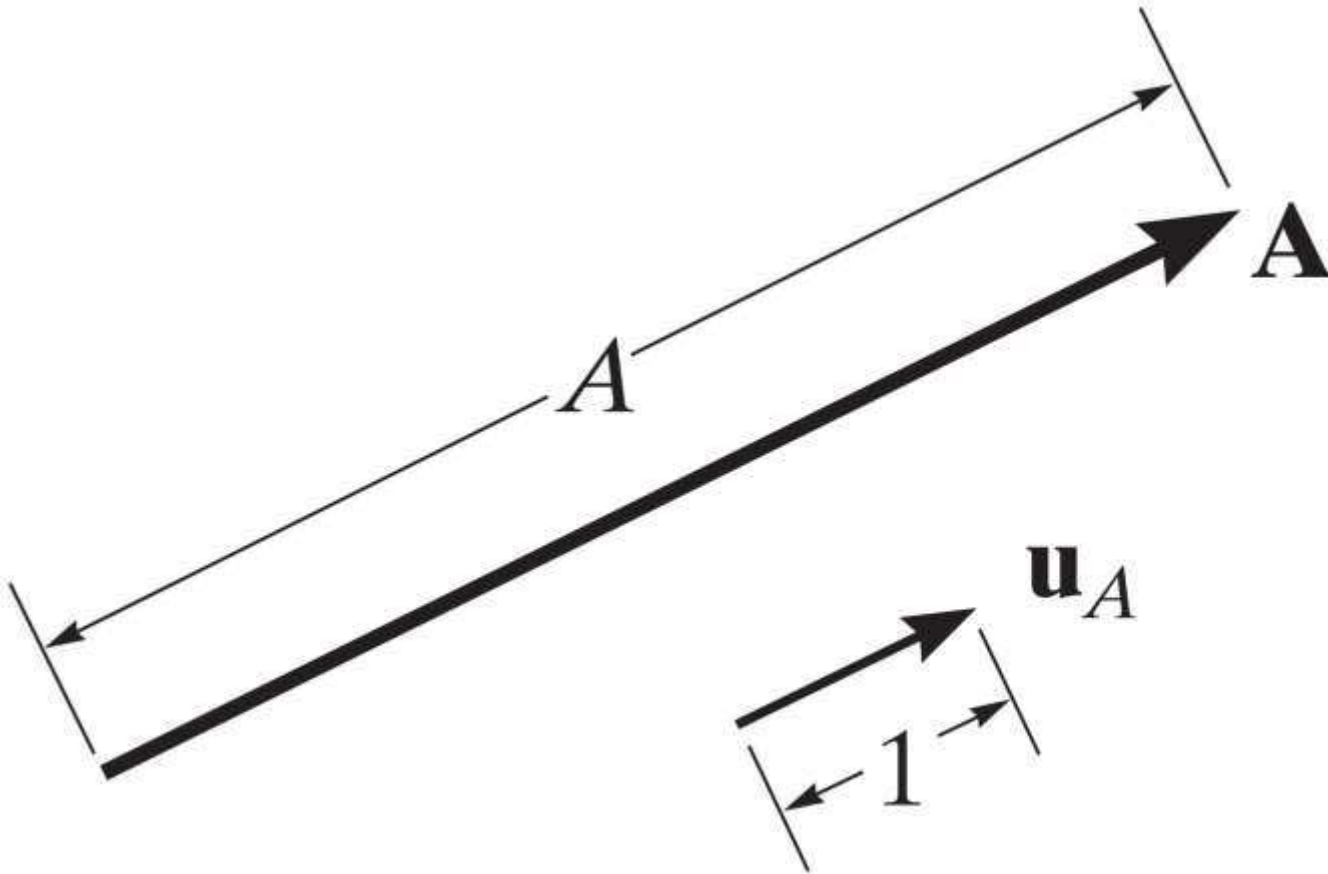
- Also note that by convention will orient axes so that **positive direction is upwards**

RECTANGULAR COMPONENTS OF A VECTOR



$$\mathbf{A} = \mathbf{A}_x + \mathbf{A}_y + \mathbf{A}_z$$

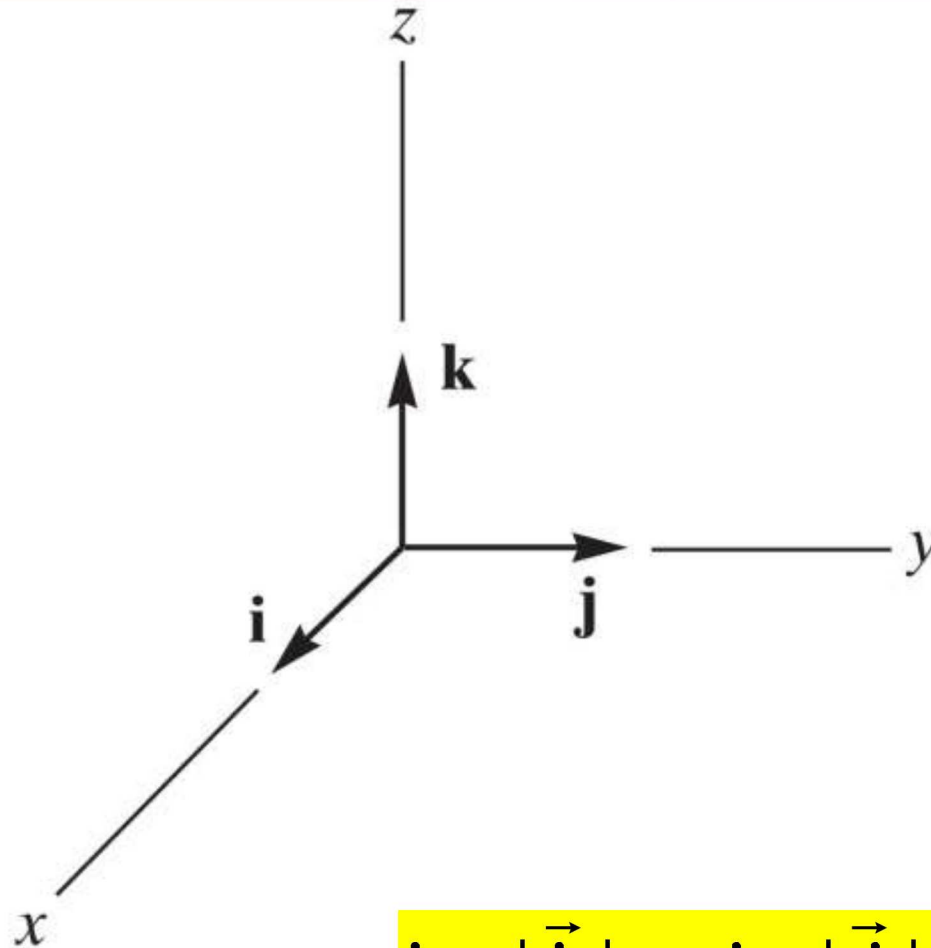
UNIT VECTOR



$$\mathbf{u}_A = \frac{\mathbf{A}}{A}$$

$$u_A = 1$$

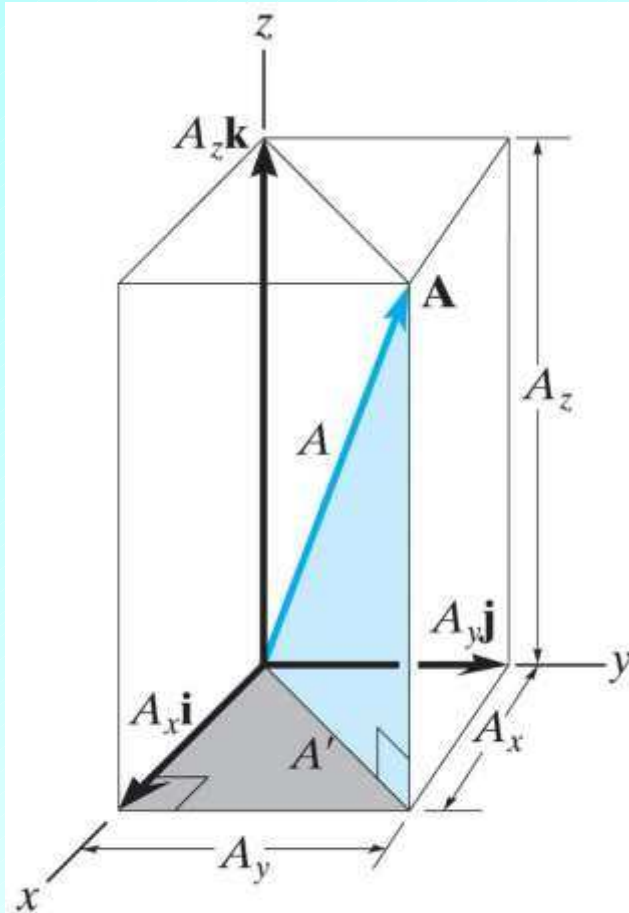
CARTESIAN UNIT VECTORS



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$$i = |\vec{i}| = j = |\vec{j}| = k = |\vec{k}| = 1$$

CARTESIAN VECTOR REPRESENTATION & MAGNITUDE OF A CARTESIAN VECTOR



$$\mathbf{A} = A_x \mathbf{i} + A_y \mathbf{j} + A_z \mathbf{k}$$

$$A = \sqrt{A_x^2 + A_y^2 + A_z^2}$$

02_025

Note that despite what the text might imply (if not state explicitly), components A_x , A_y and A_z can have either sign in general.