PHYS 410: Computational Physics Fall 2022 Final exam key

Problem 1: [10 pts]

Problem 1.1: Derivative of a polynomial interpolant [5 pts]

Consider 3 equispaced data points:

$$(-h, f_{-1}), (0, f_0), (h, f_1)$$

Construct the Lagrange interpolating polynomial for these values, then evaluate the derivative at x = 0.

$$p(x) = \sum_{j=1}^{3} f_j l_j(x) = \sum_{j=1}^{3} f_j \prod_{i=1, i \neq j}^{3} \frac{x - x_i}{x_j - x_i}$$

= $f_{-1} \frac{x(x-h)}{(-h)(-2h)} + f_0 \frac{(x+h)(x-h)}{(h)(-h)} + f_1 \frac{(x+h)(x)}{(2h)(h)}$
= $f_{-1} \frac{x^2 - hx}{2h^2} - f_0 \frac{x^2 - h^2}{h^2} + f_1 \frac{x^2 + hx}{2h^2}$

Now, since the above expression is a polynomial in x, to determine the derivative evaluated at x = 0, we simply need to read off the coefficient of the linear term of the polynomial. Thus we have

$$\left. \frac{dp}{dx} \right|_{x=0} = \frac{f_1 - f_{-1}}{2h}$$

Problem 1.2: Richardson extrapolating an $O(h^2)$ FDA [5 pts]

We are given

$$\frac{u_{j+1} - 2u_j + u_{j-1}}{\Delta x^2} = \frac{d^2u}{dx^2} + \frac{1}{12}\Delta x^2 \frac{d^4u}{dx^4} + O(\Delta x^4)$$

Truncating at the $O(\Delta x^2)$ term, we have at scales Δx and $2\Delta x$

$$L^{\Delta x}u_{j} = \frac{u_{j+1} - 2u_{j} + u_{j-1}}{\Delta x^{2}} \sim \frac{d^{2}u}{dx^{2}} + \Delta x^{2}e_{2}(x)$$
$$L^{2\Delta x}u_{j}\frac{u_{j+2} - 2u_{j} + u_{j-2}}{4\Delta x^{2}} \sim \frac{d^{2}u}{dx^{2}} + 4\Delta x^{2}e_{2}(x)$$

We now want to take a linear combination such that

$$\alpha L^{\Delta x} u_j + \beta L^{2\Delta x} u_j = \frac{d^2 u}{dx^2} + O(\Delta x^4)$$

We thus must have

 $\begin{aligned} \alpha+\beta &= 1\\ \alpha+4\beta &= 0 \end{aligned}$

Solving, we have

$$\begin{aligned} \alpha &= \frac{4}{3} \\ \beta &= -\frac{1}{3} \end{aligned}$$

Assembling results:

$$\frac{4}{3}L^{\Delta x}u_j - \frac{1}{3}L^{2\Delta x}u_j = \frac{16u_{j+1} - 32u_j + 16u_{j-1}}{12\Delta x^2} - \frac{u_{j+2} - 2u_j + u_{j-2}}{12\Delta x^2}$$

So our $O(h^4)$ approximation is

$$\frac{-u_{j+2}+16u_{j+1}-30u_j+16u_{j-1}-u_{j-2}}{12\Delta x^2}$$

Problem 2: [10 pts]

The differential equation is

$$\frac{d^2x}{dt^2} + \left(x\frac{dx}{dt}\right)^3 = s(t)$$

with initial conditions

$$x(0) = x_0$$
$$\frac{dx}{dt}(0) = v_0$$

 $\langle \alpha \rangle$

Problem 2.1: FDA [2 pts]

The FDA is

$$\frac{x^{n+1} - 2x^n + x^{n-1}}{\Delta t^2} + \left((x^n) \, \frac{x^{n+1} - x^{n-1}}{2\Delta t} \right)^3 = s^n$$

Problem 2.2: Initialization [4 pts]

We need to determine values for $x^1 = x(0)$ and $x^2 = x(\Delta t)$. The latter must be computed up to and including terms of $O(\Delta t^2)$ so that the overall scheme is $O(\Delta t^2)$. We have

$$x^1 = x_0$$

and using the equation of motion to eliminate the second time derivative in the Taylor series expansion

$$x^{2} = x^{1} + \Delta t \frac{dx}{dt}(0) + \frac{1}{2}\Delta t^{2} \frac{d^{2}x}{dt^{2}}(0) + O(\Delta t^{3})$$

$$\approx x_{0} + \Delta t v_{0} + \frac{1}{2}\Delta t^{2} \left(s(0) - \left(x(0)\frac{dx}{dt}(0)\right)^{3}\right)$$

 \mathbf{SO}

$$x^{2} = x_{0} + \Delta t v_{0} + \frac{1}{2} \Delta t^{2} \left(s(0) - (x_{0}v_{0})^{3} \right)$$

Problem 2.3: Determining x^{n+1} [4 pts]

The FDA is a *nonlinear* equation in x^{n+1} :

$$F(x^{n+1}) = \frac{x^{n+1} - 2x^n + x^{n-1}}{\Delta t^2} + \left((x^n) \frac{x^{n+1} - x^{n-1}}{2\Delta t} \right)^3 - s^n = 0$$

We can determine x^{n+1} iteratively

$$x_{(0)}^{n+1} \to x_{(1)}^{n+1} \to \dots x_{(m)}^{n+1} \to x_{(m+1)}^{n+1} \to \dots$$

using Newton's method. Start with the initial estimate

$$x_{(0)}^{n+1} = x^n$$

then generate the iterates via

$$x_{(m+1)}^{n+1} = x_{(m)}^{n+1} - \frac{F(x_{(m)}^{n+1})}{dF/dx^{n+1}|x = x_{(m)}^{n+1}}$$

where

$$\frac{dF}{dx^{n+1}} = \frac{1}{\Delta t^2} + \frac{3(x^n)^3}{8\Delta t^3} \left(x^{n+1} - x^{n-1}\right)^2$$

Problem 3 [15 pts]

Problem 3.1: FDA [2 pts]

Adopting the usual finite difference notation, the FDA is

$u_j^{n+1} - u_j^{n-1}$	$u_{j+1}^n - u_{j-1}^n + ou^n$
$2\Delta t$	$= \frac{3}{2\Delta x} + \alpha u_j$

Problem 3.2: Truncation Error [4 pts]

Compute the truncation error for the $O(h^2)$ approximation to the first derivative

$$u(x + \Delta x) = u(x) + \Delta x u'(x) + \frac{1}{2} \Delta x^2 u''(x) + \frac{1}{6} \Delta x^3 u'''(x) + O(\Delta x^4)$$
$$u(x - \Delta x) = u(x) - \Delta x u'(x) + \frac{1}{2} \Delta x^2 u''(x) - \frac{1}{6} \Delta x^3 u'''(x) + O(\Delta x^4)$$

 \mathbf{SO}

$$\frac{u(x + \Delta x) - u(x - \Delta x)}{2\Delta x} = u'(x) + \frac{1}{6}\Delta x^2 u'''(x) + O(\Delta x^4)$$

Writing the difference approximation in the form

$$\frac{u_j^{n+1} - u_j^{n-1}}{2\Delta t} - \frac{u_{j+1}^n - u_{j-1}^n}{2\Delta x} - \alpha u_j^n = 0$$

the truncation error is

$$\tau = \frac{1}{6}\Delta t^2 u_{ttt} - \frac{1}{6}\Delta x^2 u_{xxx}$$

Problem 3.3: Initialization [4 pts]

To guarantee an $O(h^2)$ accurate solution at any fixed (t, x) we need to know u_j^2 to $O(\Delta t^2)$ accuracy. Taylor series expanding, we have

$$u(x,\Delta t) = u(x,0) + \Delta t u_t(x,0) + \frac{1}{2} \Delta t^2 u_{tt}(x,0) + O(\Delta t^3)$$
(1)

Now, from the initial conditions we have $u(x, 0) = u_0(x)$, and from the governing PDE we have

$$u_t(x,0) = u_x(x,0) + \alpha u(x,0) = u'_0 + \alpha u_0$$

$$u_{tt}(x,0) = (u_x(x,0) + \alpha u(x,0))_t = u_{xt}(x,0) + \alpha u_t(x,0) = u_{tx}(x,0) + \alpha u_t(x,0)$$
$$= u_0'' + \alpha u_0' + \alpha u_0' + \alpha^2 u_0 = u_0'' + 2\alpha u_0' + \alpha^2 u_0$$

Substituting in (1) we have

$$\begin{bmatrix} u_j^1 = u_{0_j} \\ u_j^2 = u_{0_j} + \Delta t \left(u_0' + \alpha u_0 \right)_j + \frac{1}{2} \Delta t^2 \left(u_0'' + 2\alpha u_0' + \alpha^2 u_0 \right)_j \end{bmatrix}$$

Problem 3.4: Stability Analysis [5 pts]

First, according to a theorem quoted without proof in class, we can neglect undifferentiated terms when performing a von Neumann stability analysis.

Second, rewrite the difference equation in "first order" form, introducing $v_i^n = u_i^{n-1}$:

$$\begin{array}{lll} u_{j}^{n+1} & = & v_{j}^{n} + \lambda \left(u_{j+1}^{n} - u_{j-1}^{n} \right) \,, \\ v_{j}^{n+1} & = & u_{j}^{n} \,, \end{array}$$

where $\lambda = \Delta t / \Delta x$. In matrix form

$$\left[\begin{array}{c} u\\v\end{array}\right]^{n+1} = \left[\begin{array}{cc} \lambda D_0 & 1\\1 & 0\end{array}\right] \left[\begin{array}{c} u\\v\end{array}\right]^n$$

where $D_0 u_j^n = u_{j+1}^n - u_{j-1}^n$. Under Fourier transformation this becomes

$$\begin{bmatrix} \tilde{u} \\ \tilde{v} \end{bmatrix}^{n+1} = \begin{bmatrix} 2i\lambda\sin\xi & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} \tilde{u} \\ \tilde{v} \end{bmatrix}^n$$

where $\xi = kh$ as usual. We must now determine conditions under which the above matrix has eigenvalues that lie within or on the unit circle. The characteristic equation is

$$\begin{vmatrix} 2i\lambda\sin\xi - \mu & 1\\ 1 & -\mu \end{vmatrix} = 0$$

or

$$\mu^2 - (2i\lambda\sin\xi)\,\mu - 1 = 0\,.$$

This equation has roots at

$$\mu(\xi) = i\lambda\sin\xi \pm \sqrt{1 - \lambda^2\sin^2\xi}$$

 $|\mu(\xi)| \le 1,$

 $|\mu(\xi)|^2 \le 1.$

Need sufficient conditions for

or equivalently

Two cases to consider

1.
$$1 - \lambda^2 \sin^2 \xi \ge 0 \rightarrow \lambda \le 1$$

2. $1 - \lambda^2 \sin^2 \xi < 0 \rightarrow \lambda > 1$

Case 1

 $|\mu(\xi)|^2=\lambda^2\sin^2\xi+1-\lambda^2\sin^2\xi=1,$ so we have von Neumann stability. Case 2

The argument of the square root is negative for sufficiently large ξ so the square root itself is purely imaginary. Together with the fact that $|i\lambda\sin(\xi)| > 1$ this implies that $\mu(\xi) > 1$ for large ξ , so we have von Neumann instability.

Thus, the von Neumann stability criterion for this scheme is

$$\lambda \leq 1$$